

Dynamic Transit Modeling

(User Equilibrium + System Optimal)



North Carolina A&T State University
Assistant Professor
John Park



05 Dual B.S.
PHYSICS +
URBAN PLAN. & ENG.

07-09
CIVIL ENGINEER



10-16
RESEARCH
ASSIST.

16 PhD
CIVIL ENG.

16-17 PostDoc
CIVIL & ENVIRON. ENG.

17- Assist. Prof.
COMPU. SCI.. ENG.



18- Affiliate
NASA



07 M.S.
TRANSPORTATION

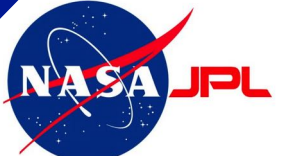
10
RESEARCH SCIENTIST



14-15
ONSITE CONTRACTOR



Massachusetts
Institute of
Technology





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10
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SEOUL MPO BUS
INFORMATION
SYSTEMS



10-16
RESEARCH
ASSIST.

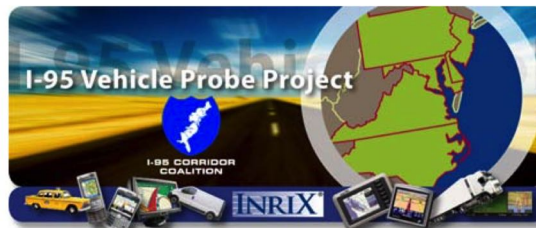
16 PhD
CIVIL ENG.



14-15
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I-95 CORRIDOR VEHICLE
PROBE PROJECT: INRIX
VALIDATION



16-17 PostDoc
CIVIL & ENVIRON. ENG.

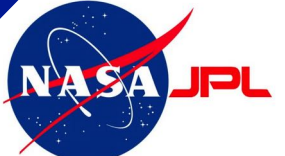


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NASA



MULTIMODAL TRANSPORTATION
INCENTIVIZING TRAVELERS WITH
PREDICTION, OPTIMIZATION AND
PERSONALIZATION



CURRENT PROJECTS

★ Traveler Decision Making



- Pedestrian
Dynamics
Evacuation



- Vulnerable
Road User
Routing

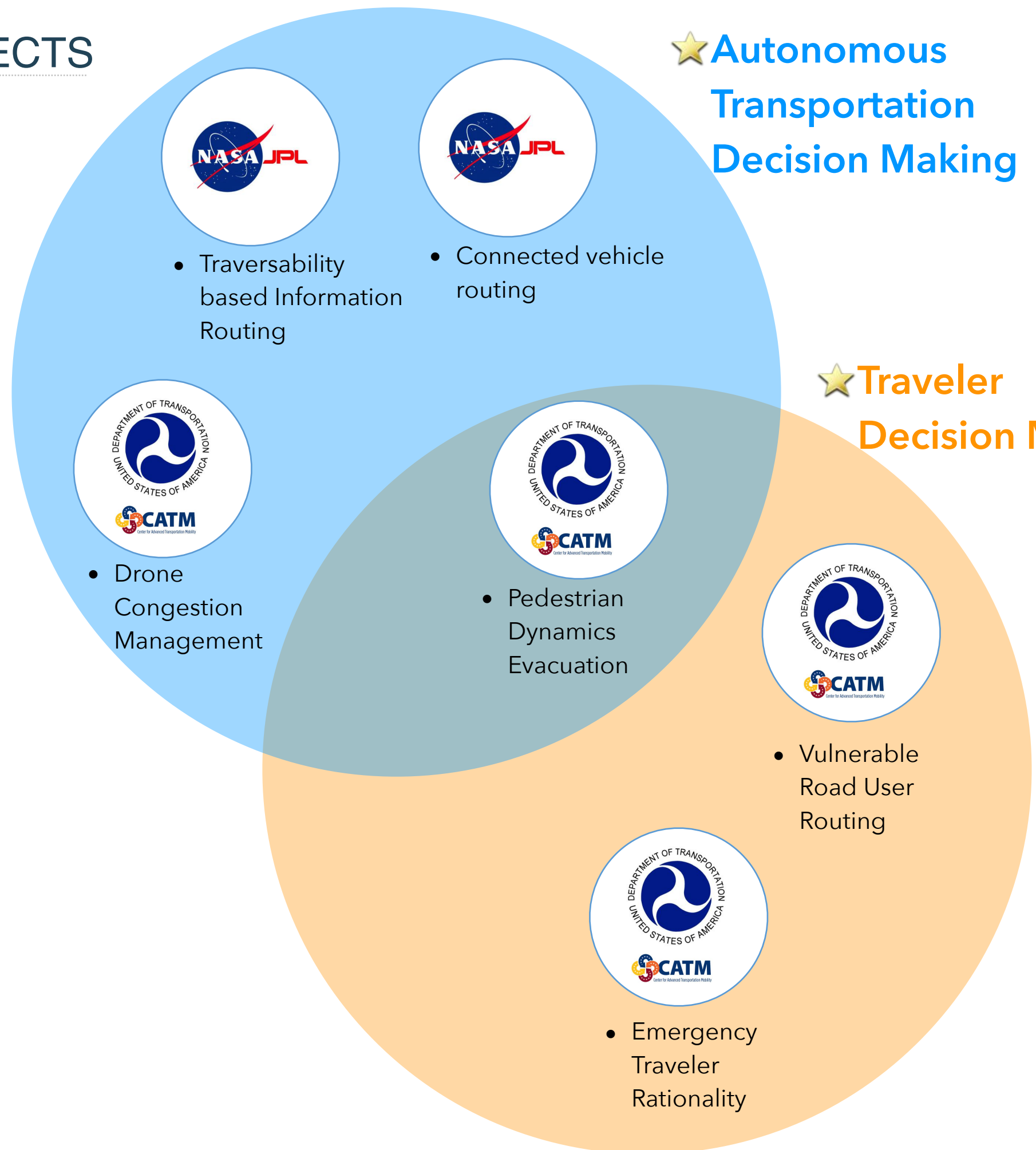


- Emergency
Traveler
Rationality

CURRENT PROJECTS

★ Autonomous Transportation Decision Making

★ Traveler Decision Making

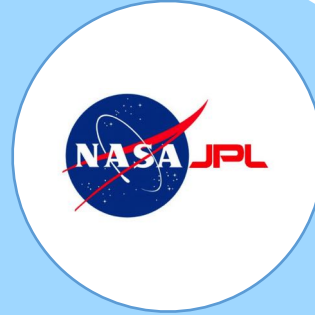


CURRENT PROJECTS

★ Autonomous Transportation Decision Making



- Traversability based Information Routing



- Connected vehicle routing

★ Traveler Decision Making



- Pedestrian Dynamics Evacuation



- Vulnerable Road User Routing

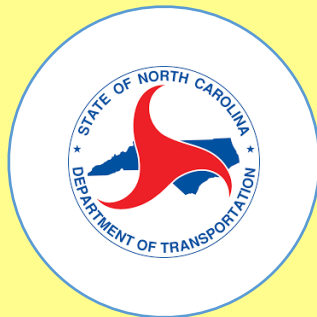


- Emergency Traveler Rationality

Multimodal Transport



- Drone Congestion Management



- Drone Traffic counting



- Truck Placard Reader

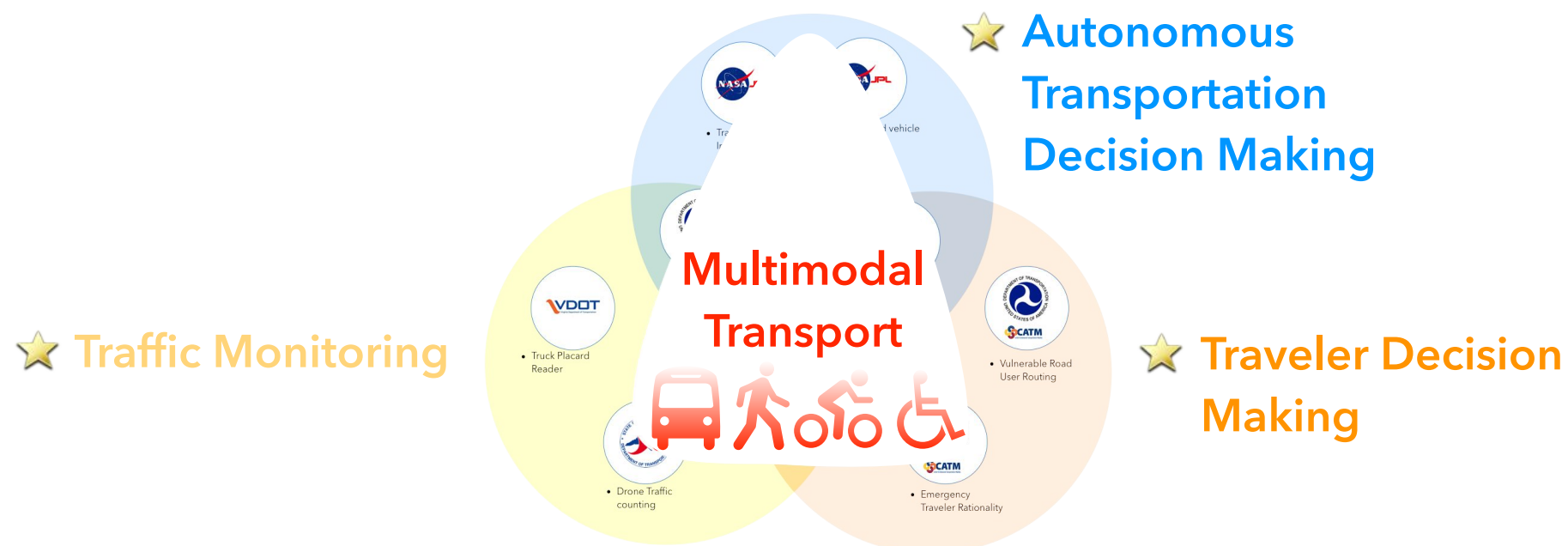
★ Traffic Monitoring

THREE CONTRIBUTIONS

1. Walk + Transit network fully integrated in a dynamic transit for various travelers.

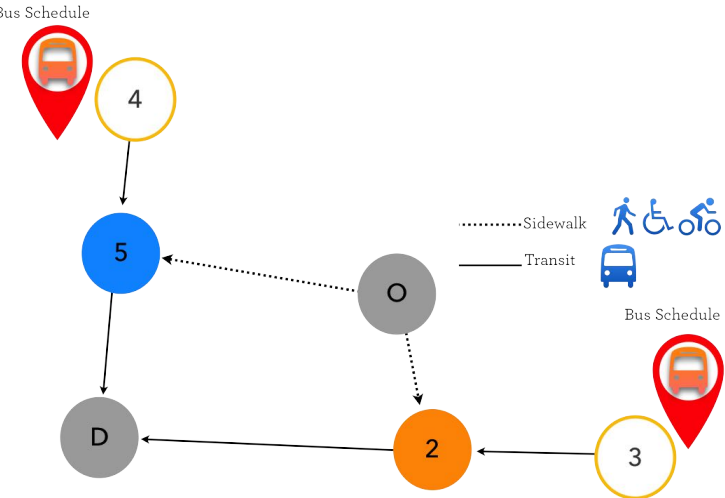
2. Motivating travelers to switch to public transit with an app-based trip planner.

3. Cloud source managing missing information with uncertainty

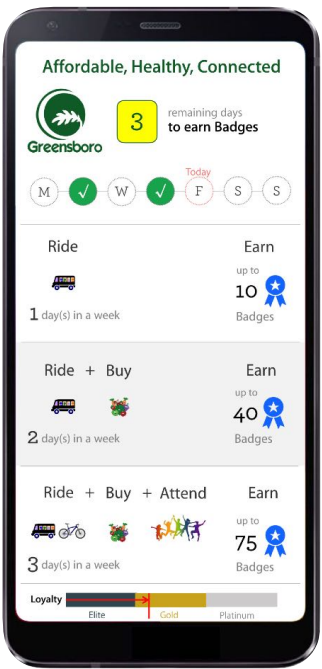


THREE CONTRIBUTIONS

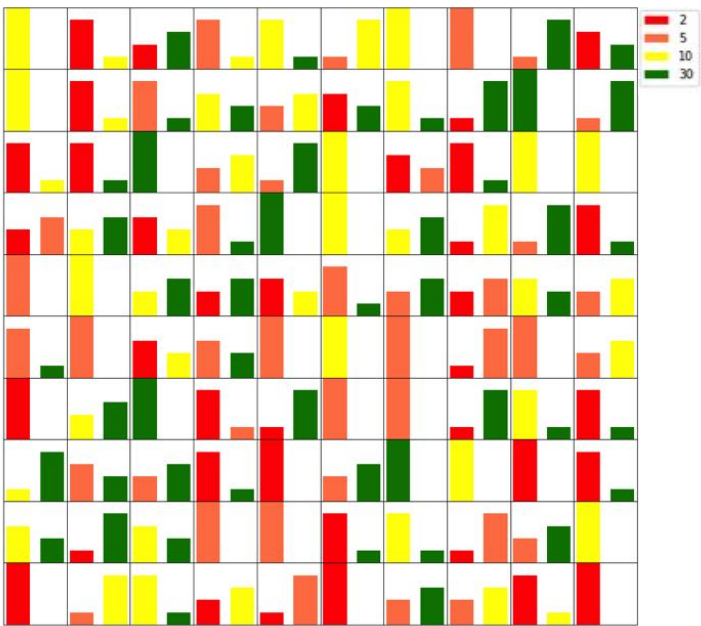
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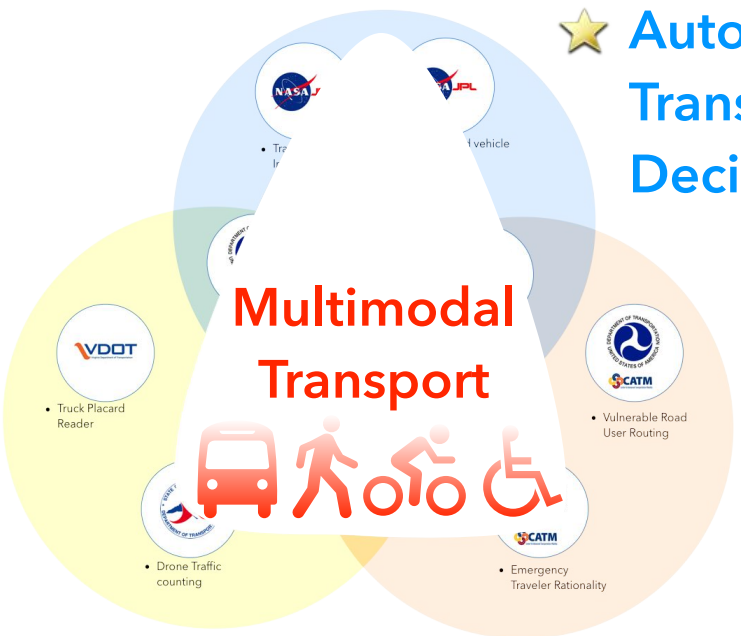
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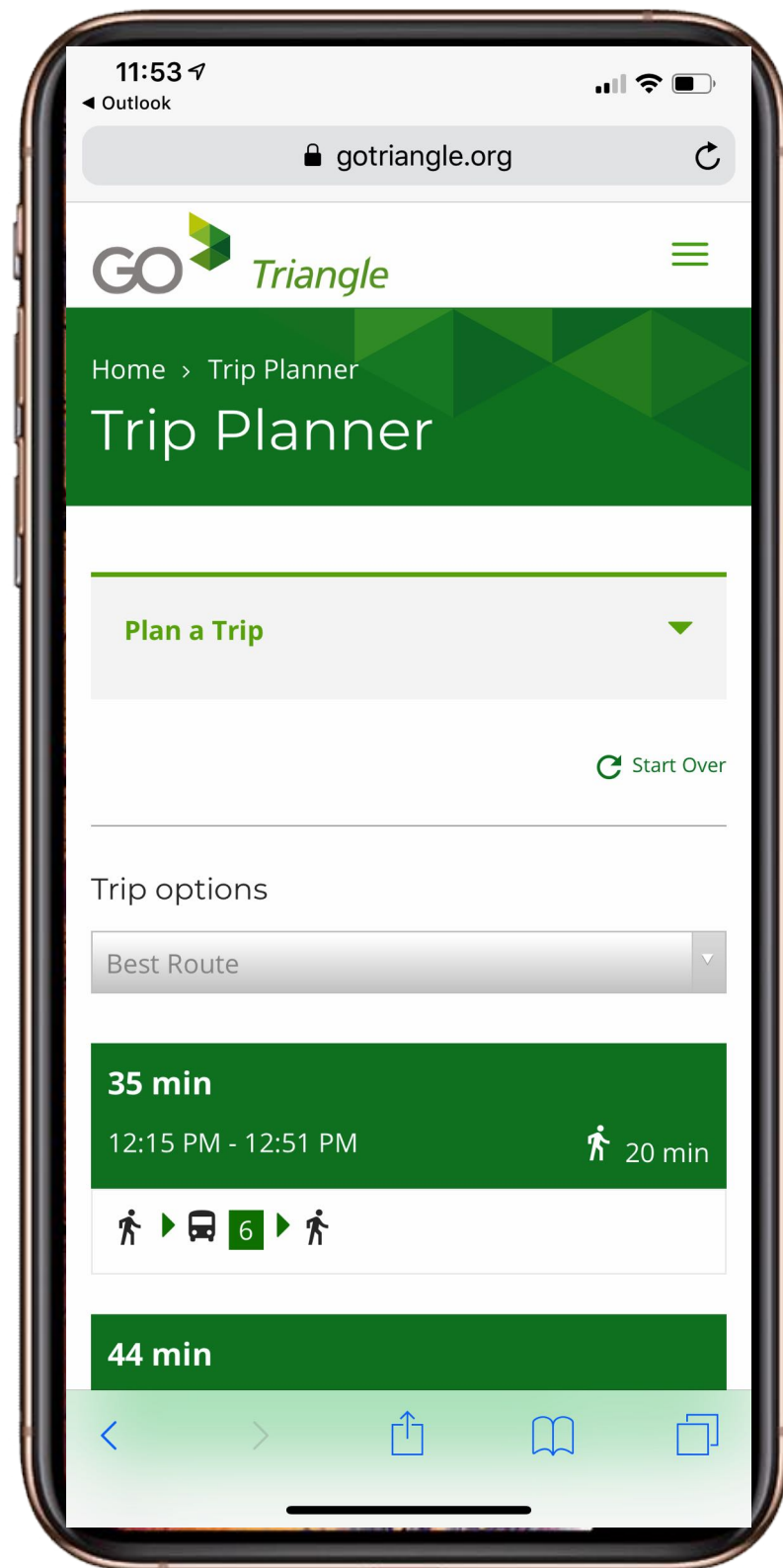
★ Traffic Monitoring



★ Autonomous Transportation Decision Making

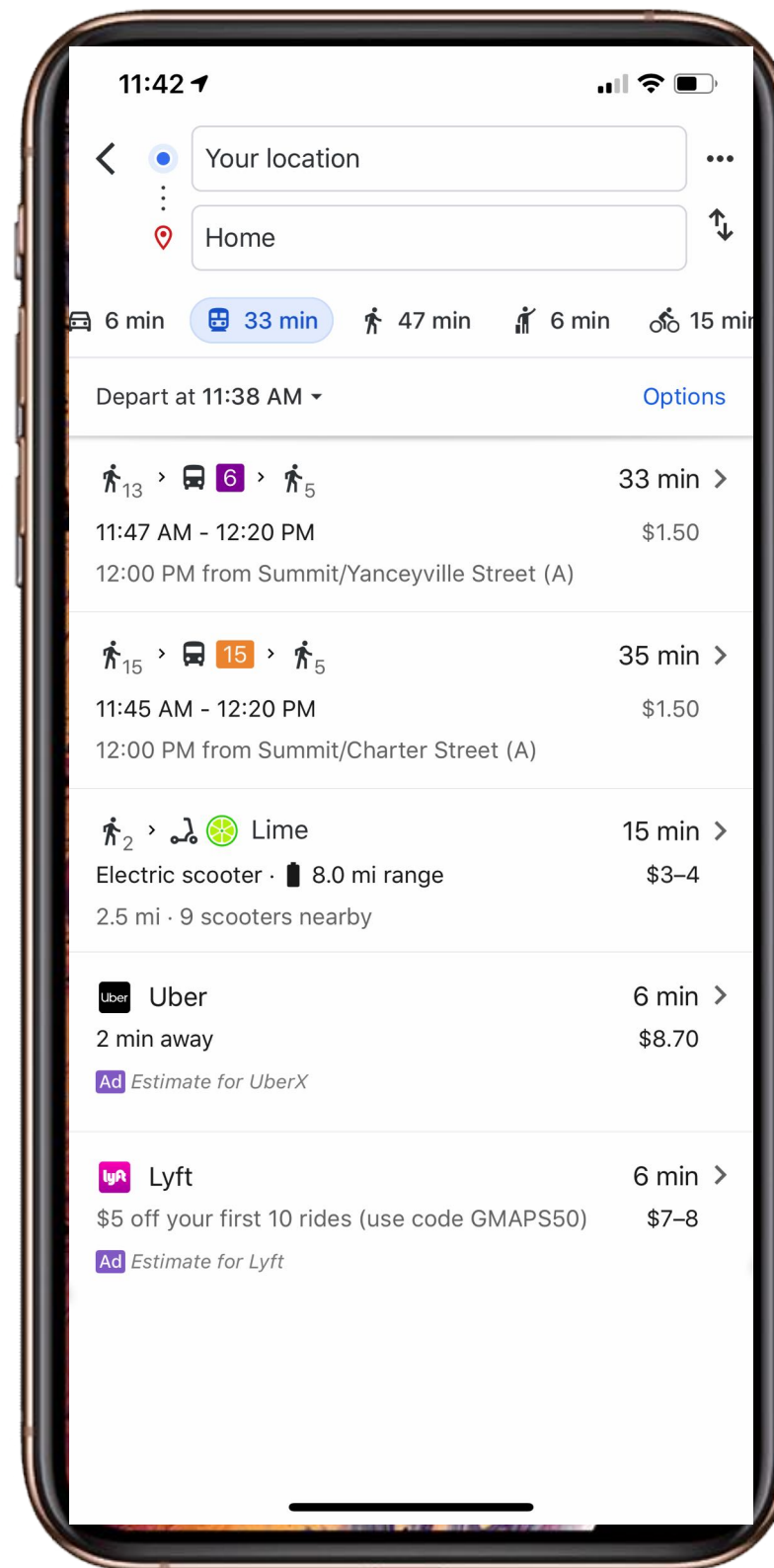
★ Traveler Decision Making

EXISTING TRIP PLANNER



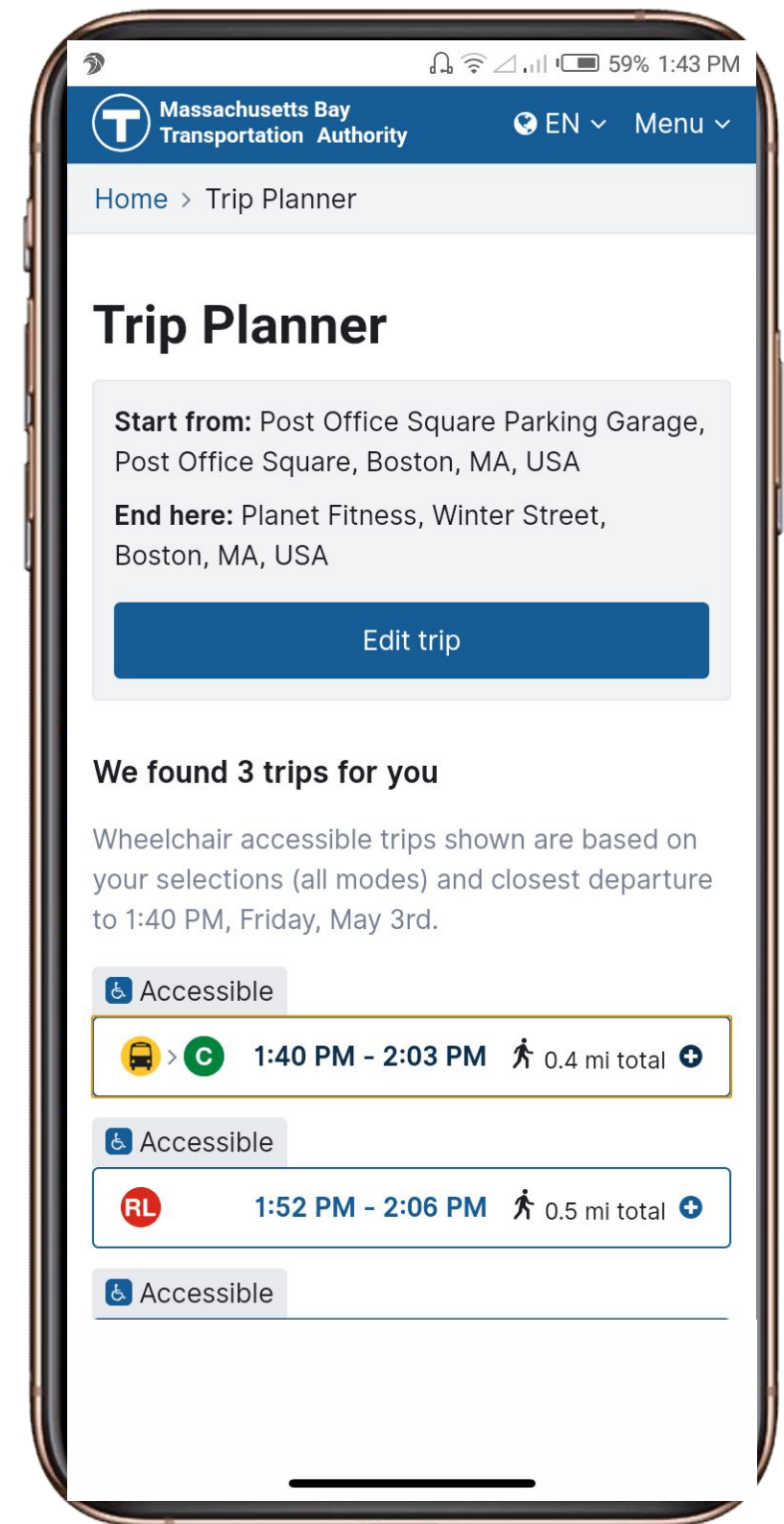
- Full & flexible Multimodal

- ★ Lacks bikes, scooters options: may not provide best multimodal route option for an individual.



- Exclusive Wheelchair user

- ★ Transit cannot be integrated with wheelchair users



- Dynamic adaptive trip planner

- ★ Recalculation of static version, failing to capture dynamic network conditions

CASE STUDY FOR PEOPLE WITH DISABILITIES

Plan a Trip

Start Over

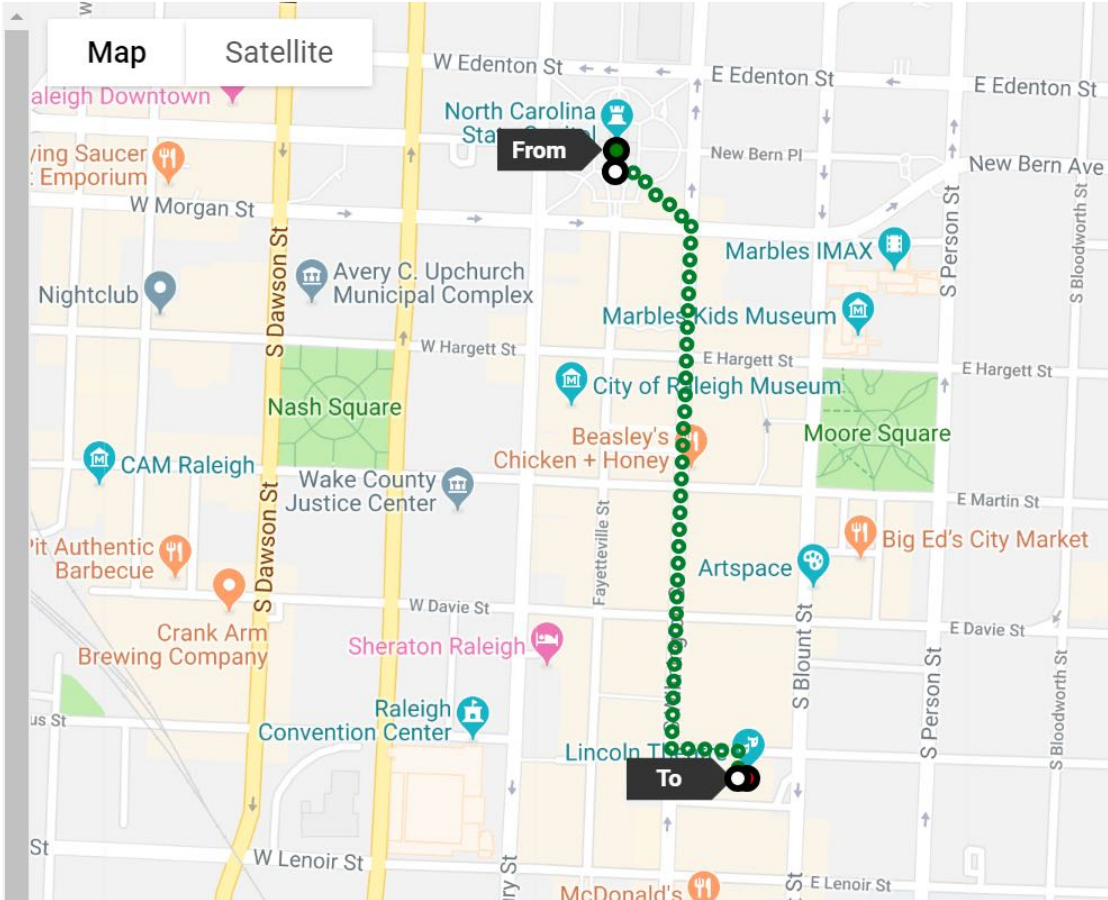
Trip options

Best Route

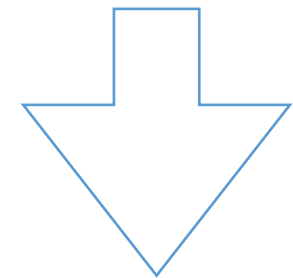
10 min

10 min

Capitol Building, Raleigh, NC 27601, USA



★ Non wheelchair accessible walking route option from go triangle trip planner



Plan a Trip

Start Over

Trip options

Best Route

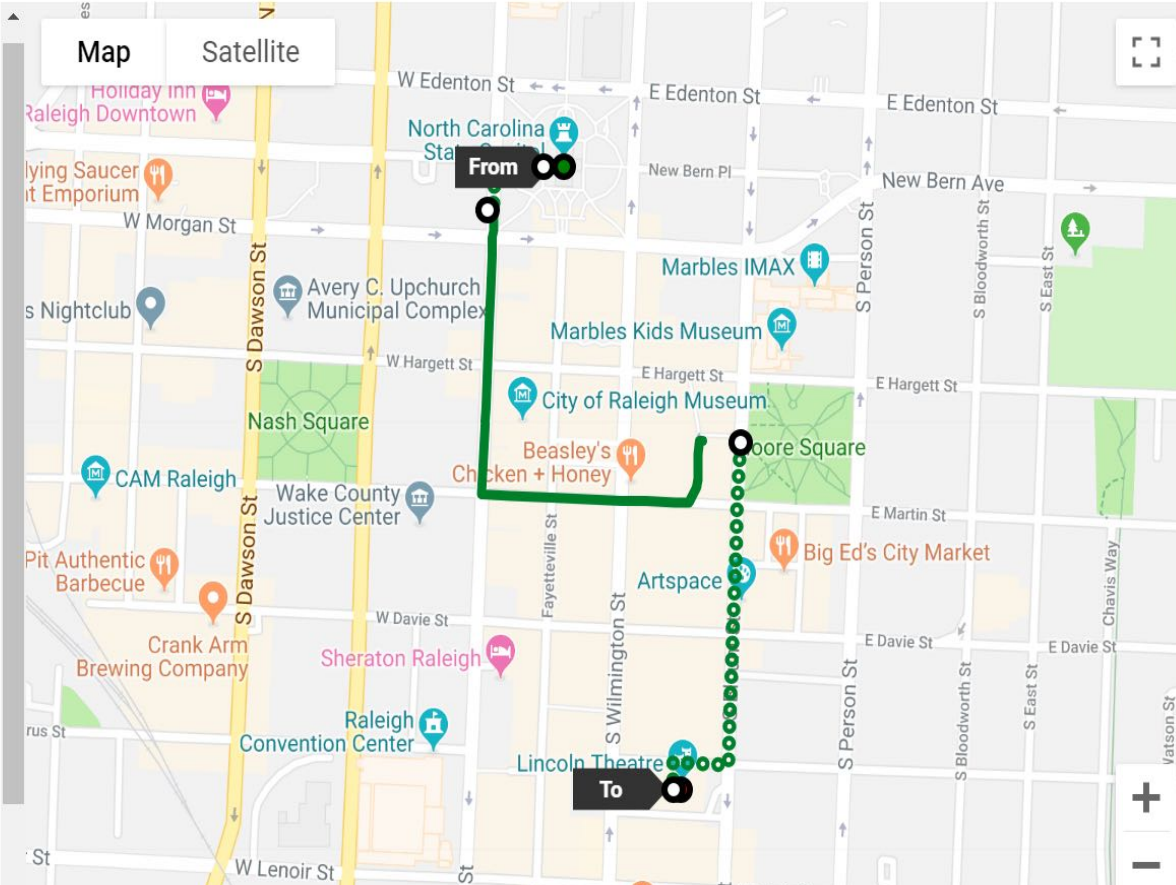
10 min

10 min

11 min

12:04 AM - 12:15 AM

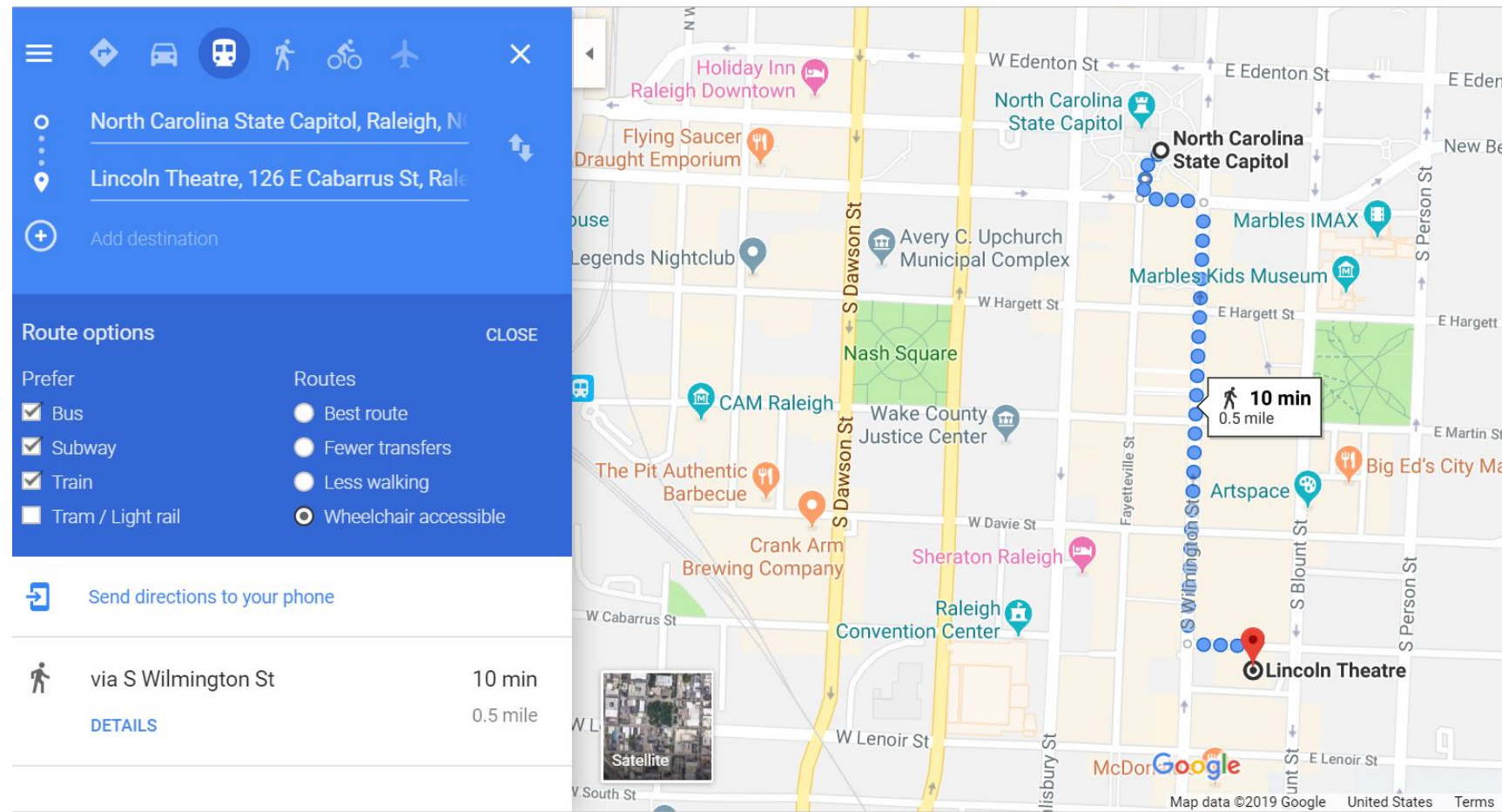
7 min



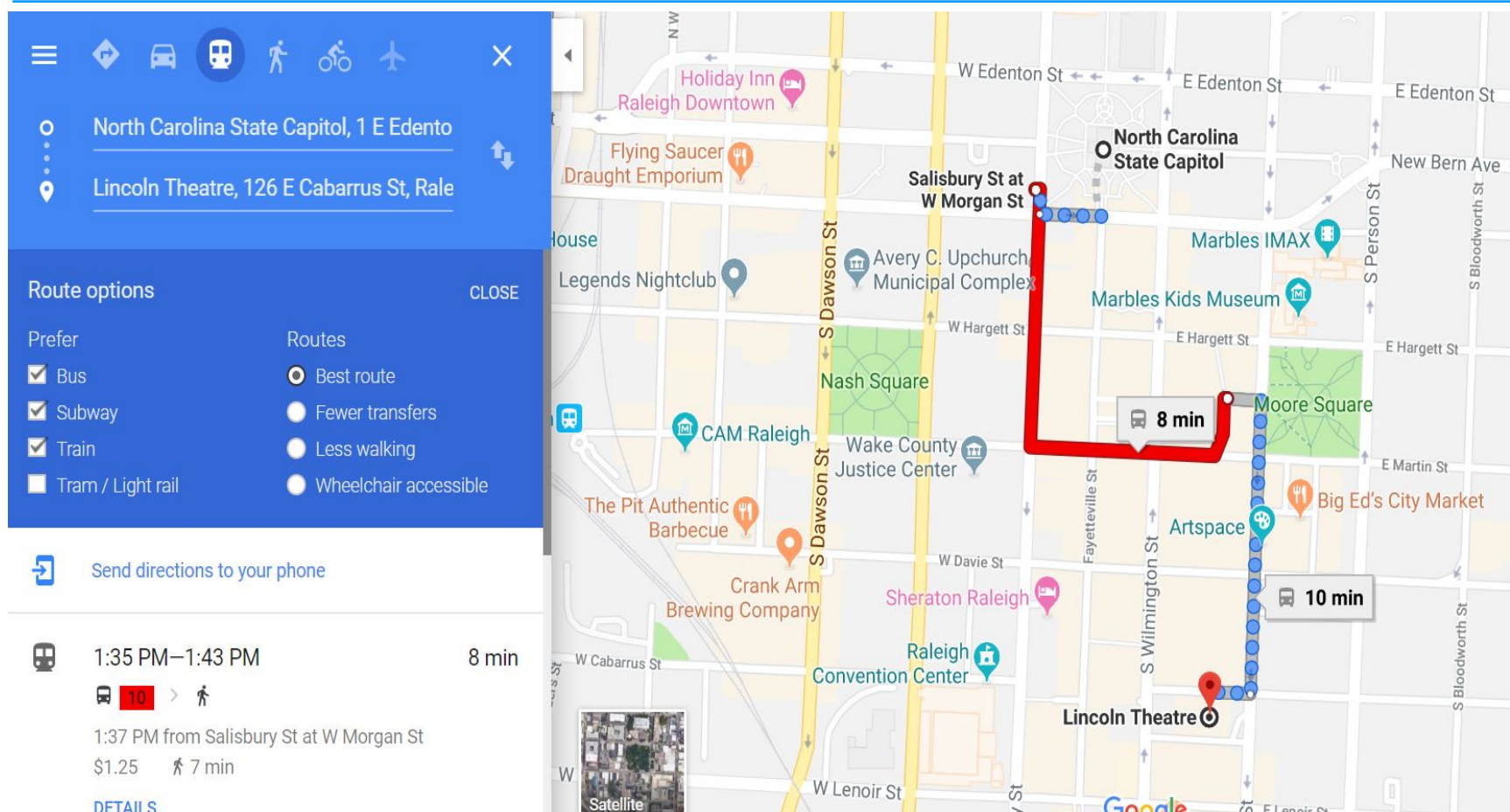
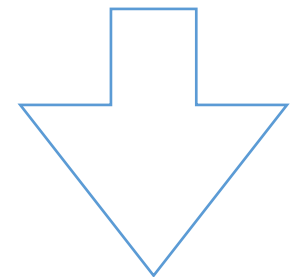
★ Non wheelchair accessible route incorporating transit from go triangle trip planner



CASE STUDY FOR PEOPLE WITH DISABILITIES

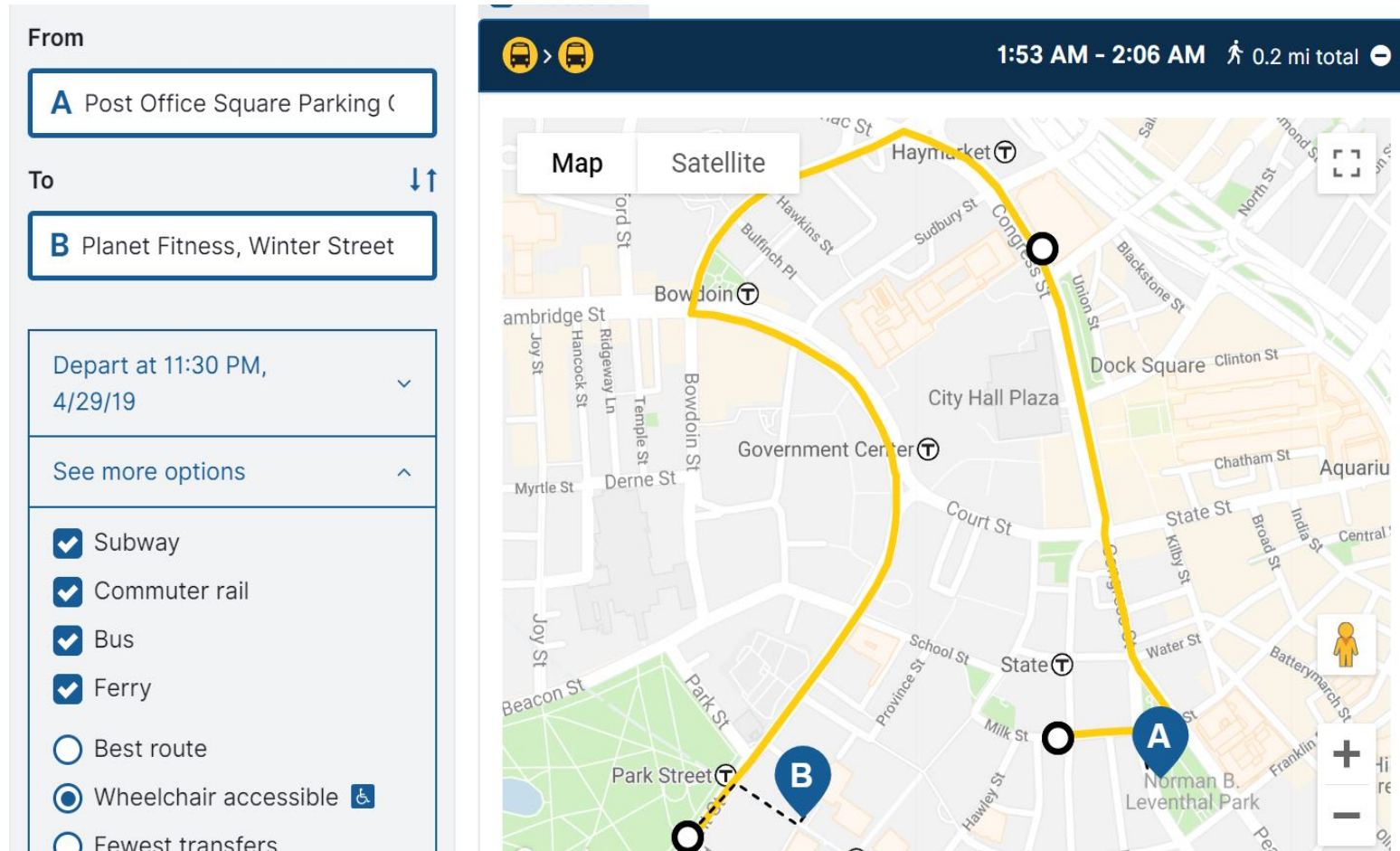


★ You can choose wheelchair accessible options, but Google Map cannot be integrate wheelchair accessible transit and Americans with Disabilities Act (ADA)

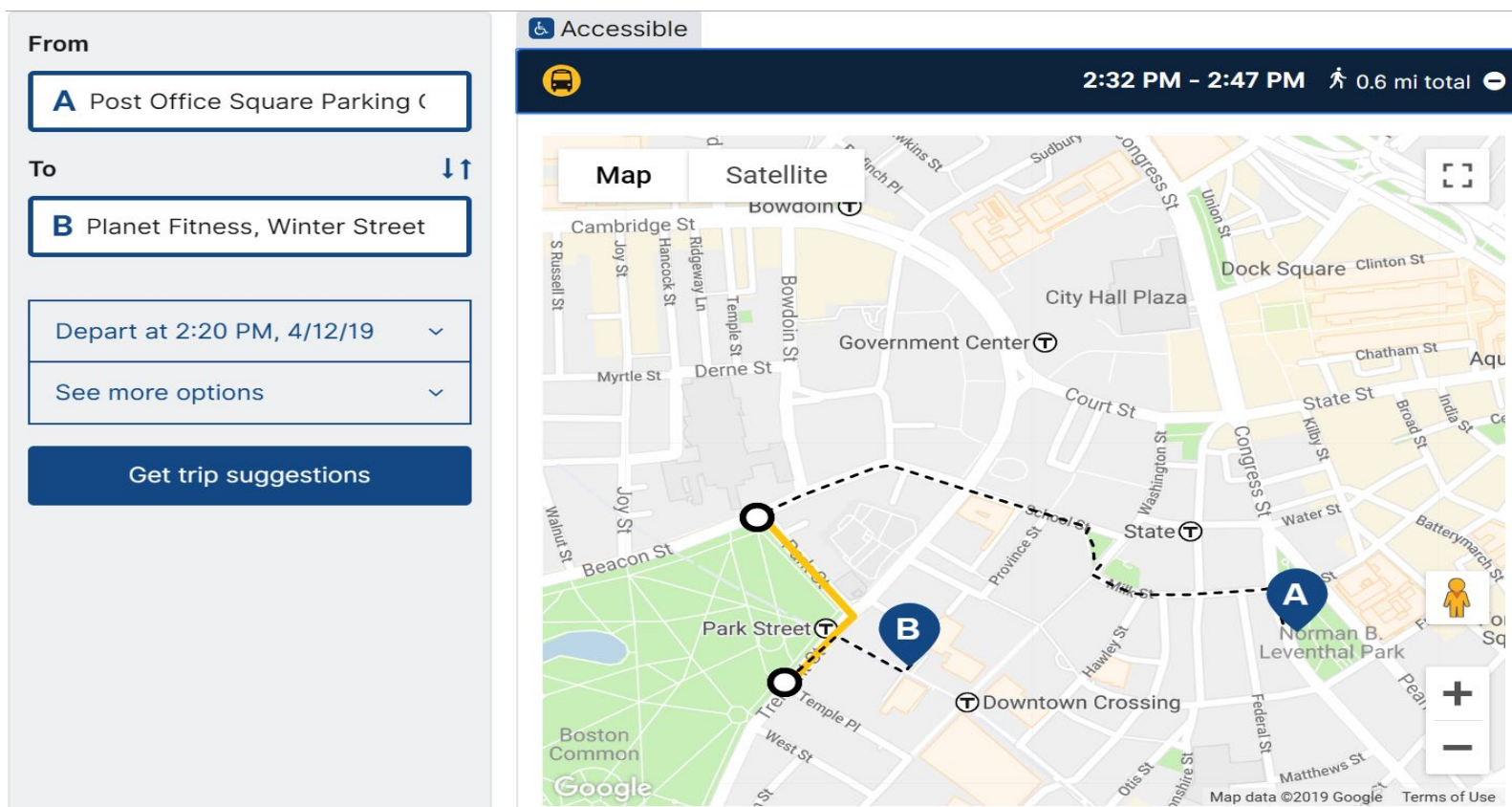
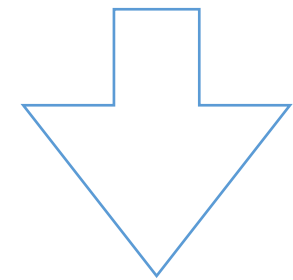


★ Best route option does not necessary good for wheelchair users.

CASE STUDY FOR PEOPLE WITH DISABILITIES



★ Minimum wheel chair travel time but longer transit time



★ Longer wheelchair travel time

State-of-the-Art App Limitations

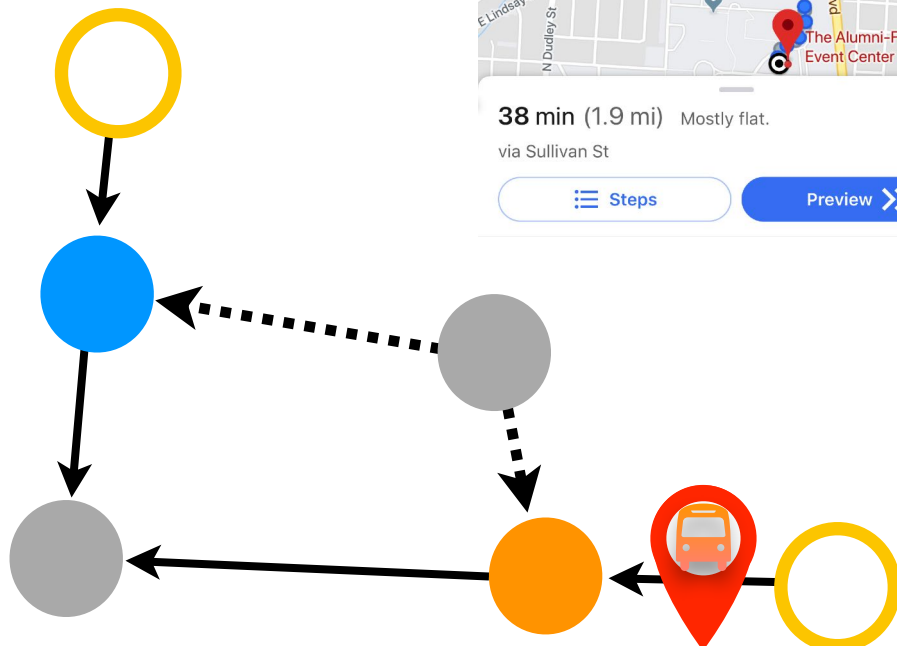
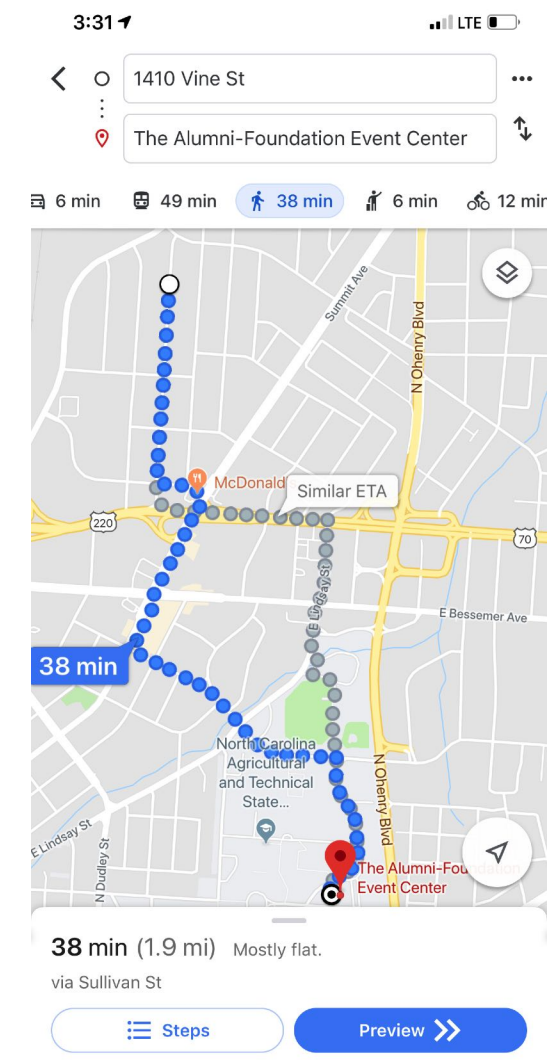
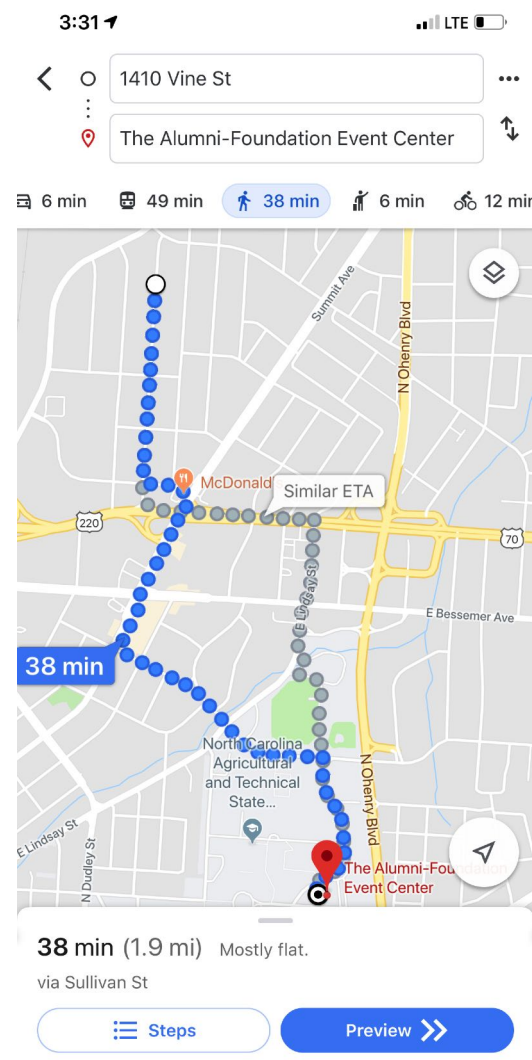
1. **Cost** function should change when **dynamic** events occurs (construction site).
2. Time-dependent network condition change (**transit on-time arrival**) makes the path cost time-dependent.
3. **Interactions** between factors contributing to the path choice also **changes by time**.

CASE STUDY FOR PEOPLE WITH DISABILITIES

★ Assist people who have physical or other disabilities with non-driving navigation of the built environment

★ I'd walk to NCDOT Summit!

★ I'd walk to NCDOT Summit!



CASE STUDY FOR PEOPLE WITH DISABILITIES

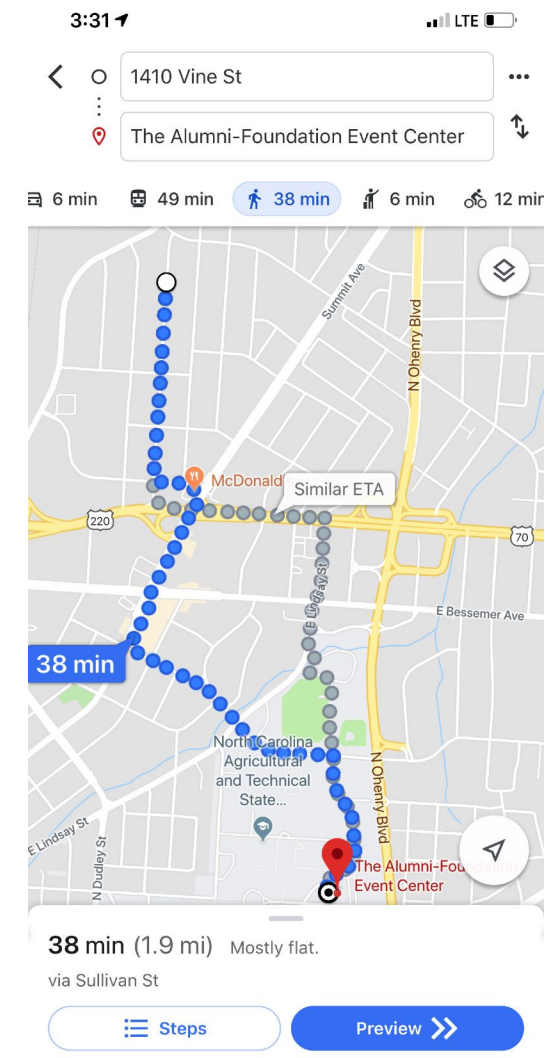
1. Dynamic Cost

2. Transit on time-arrival

3. Time-dependent interaction

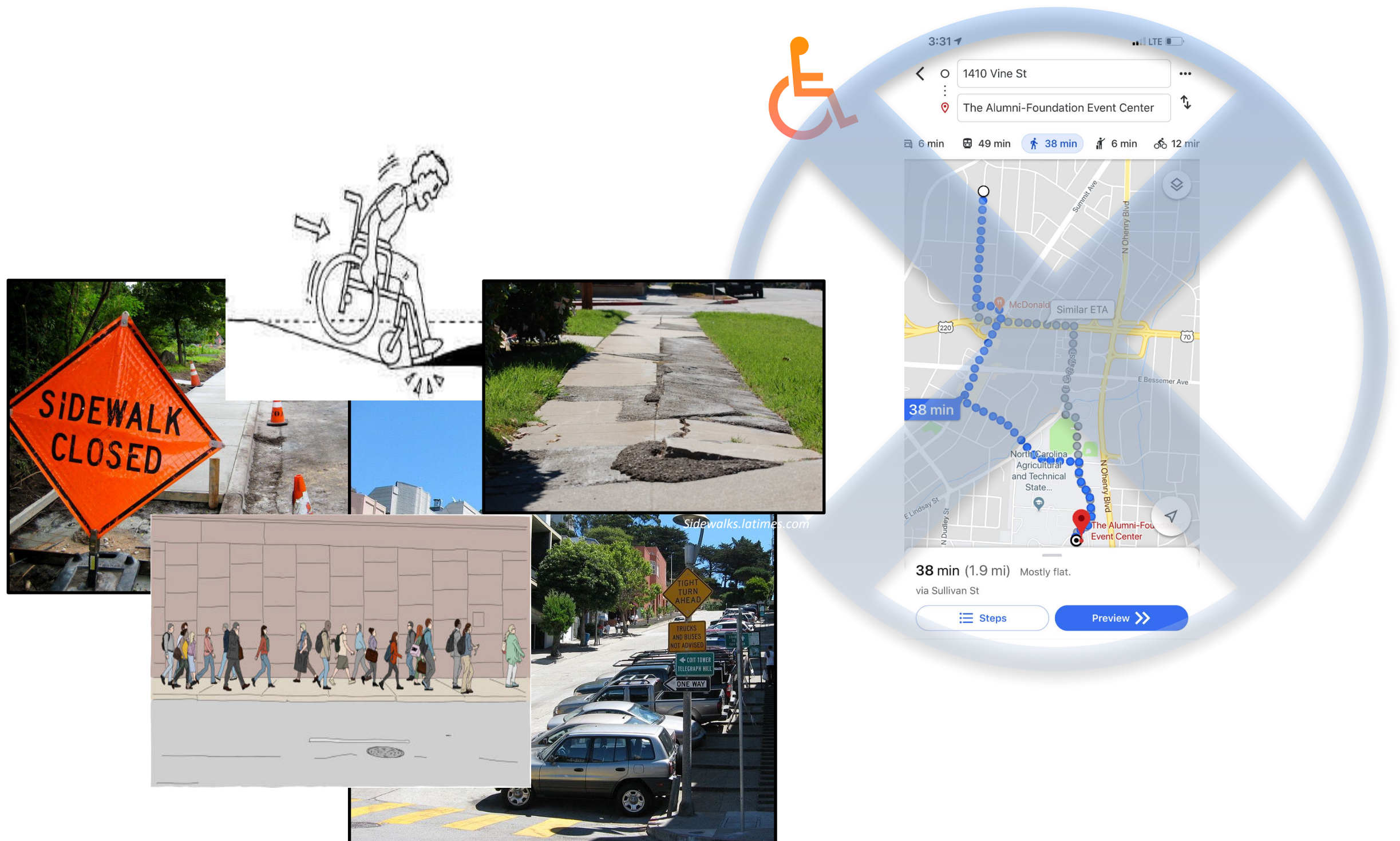
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★ Assist people who have physical or other disabilities with non-driving navigation of the built environment

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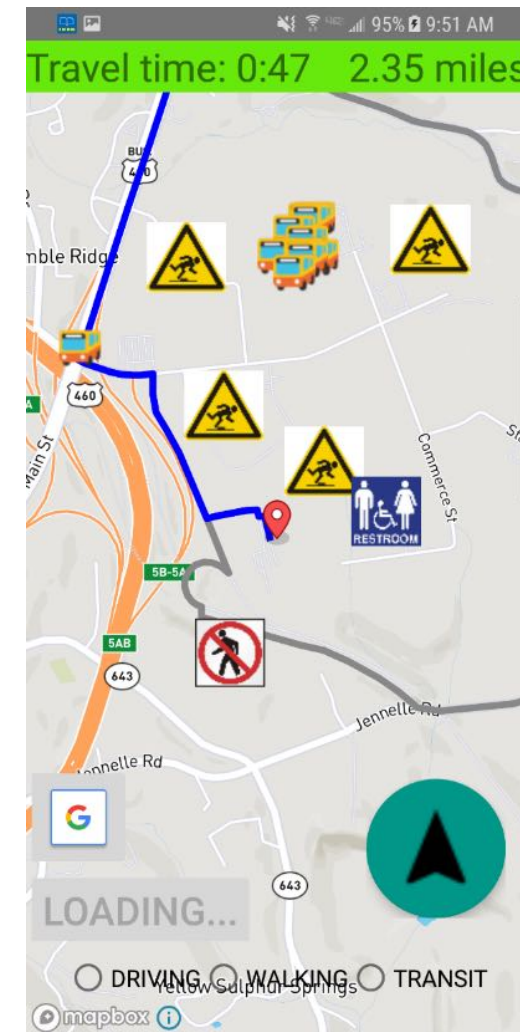
CASE STUDY FOR PEOPLE WITH DISABILITIES

1. Dynamic Cost

2. Transit on time-arrival

3. Time-dependent interaction

- ★ Assist people who have physical or other disabilities with non-driving navigation of the built environment
- ★ Combine personal capabilities with external information to result in a flexible personalized assistance platform



Sponsored by



In collaboration with

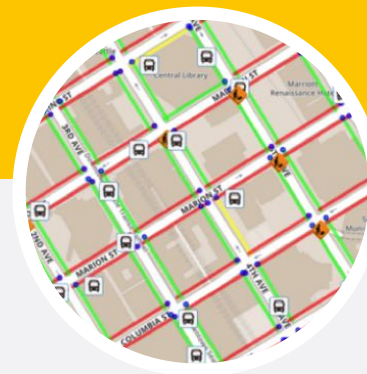


Justin Owens, Andrew Miller

STATIC & DYNAMIC UTILITIES

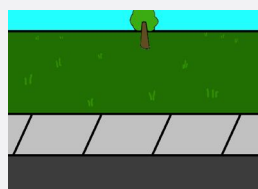
Interactions between factors change by **time**

- Wheelchair user more limited with **steep** slope (elevation) in inclement **weather**.
- Transit on-time arrival change the importance of **travel time** over **elevation**.



STATIC PARAMETERS

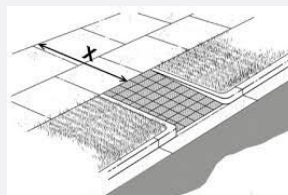
- Sidewalk width
- Sidewalk surface
- Sidewalk elevation



Surface



Elevation



Width



DYNAMIC UNEXPECTED PARAMETERS

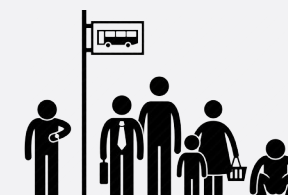
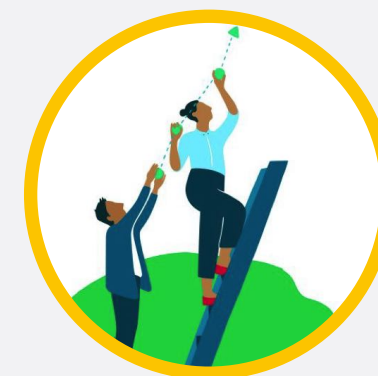
- Construction
- Bus delay
- Weather condition



Weather conditions



Construction



Bus delay

DYNAMIC PREDICTABLE PARAMETERS

- Bus delay
- Weather condition
- Congestion sidewalk



Congested sidewalk

PREDICTIVE & REAL-TIME TRANSPORT

1. Dynamic Cost

2. Transit on time-arrival

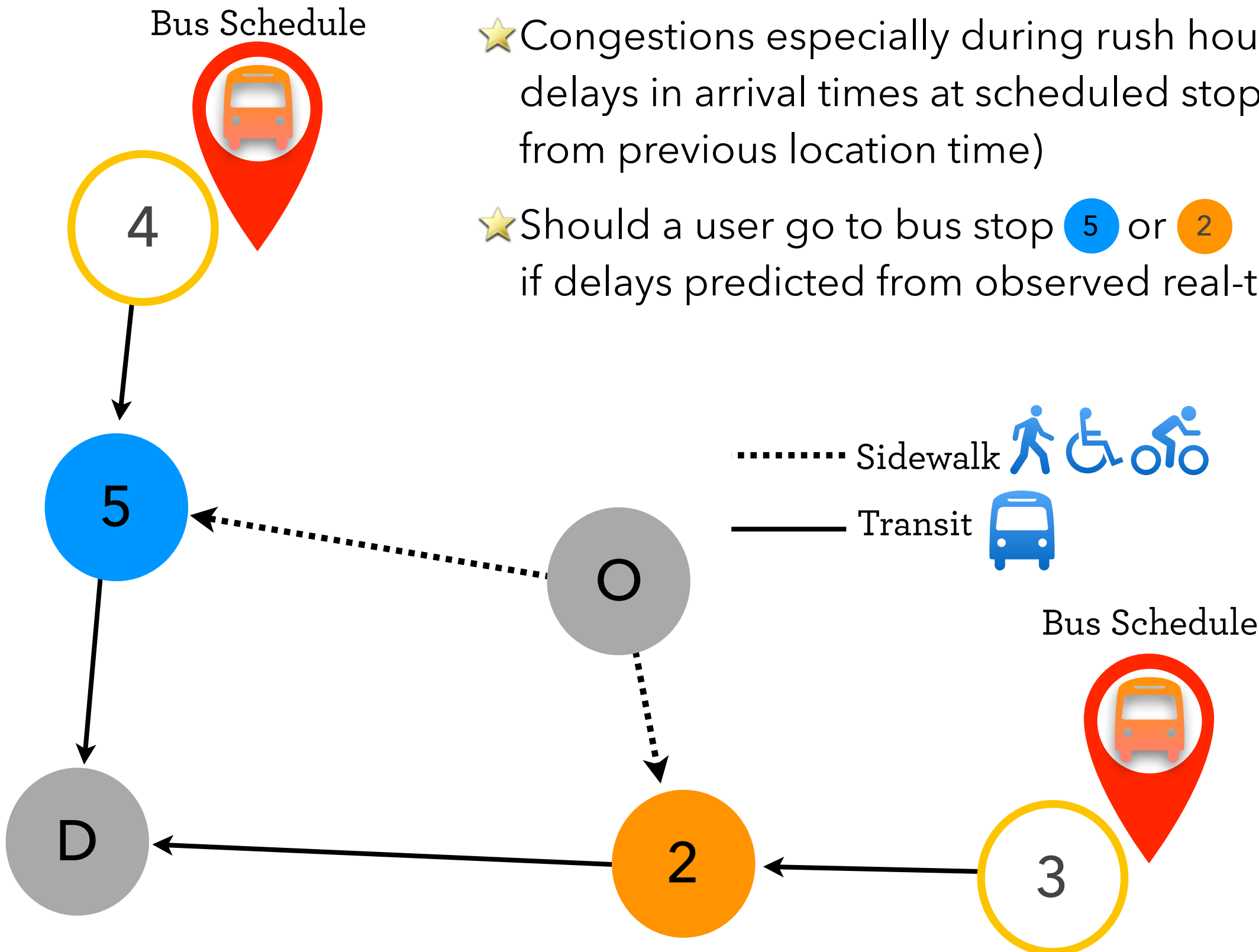
3. Time-dependent interaction

★ Each $O-D$, traveler multimodal options sidewalk (bike, walk) or transit (bus) available.

★ Congestions especially during rush hour introduces delays in arrival times at scheduled stops (predicted from previous location time)

★ Should a user go to bus stop 5 or 2 if delays predicted from observed real-time data?

Bus Schedule



PREDICTIVE & REAL-TIME TRANSPORT

1. Dynamic Cost

2. Transit on time-arrival

3. Time-dependent interaction

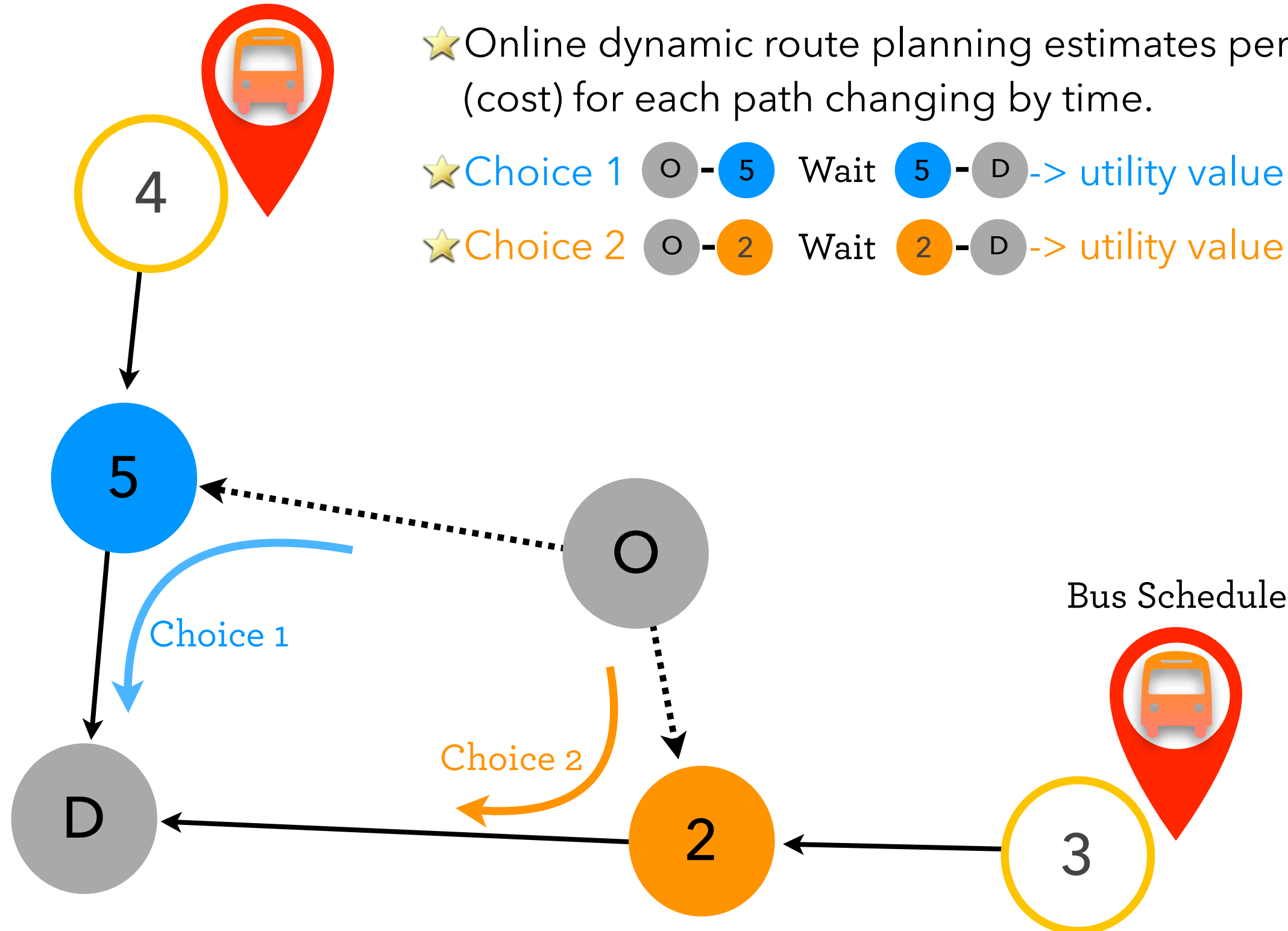
★ Personalized cloud-source real-time data improve mobility with the best multimodal transport options with waiting time at 2 and 5

★ Online dynamic route planning estimates personalized utility (cost) for each path changing by time.

★ Choice 1 ○ - 5 Wait 5 - D -> utility value for user 10?

★ Choice 2 ○ - 2 Wait 2 - D -> utility value for user 7?

Bus Schedule



CASE STUDY FOR PEOPLE WITH DISABILITIES

1. Dynamic Cost

2. Transit on time-arrival

3. Time-dependent interaction

- ★ Okay I know your preferences, then why don't you just recalculate the utility every time something unexpected event happens?
- ★ Interactions between factors contributing to the path choice also changes by time.

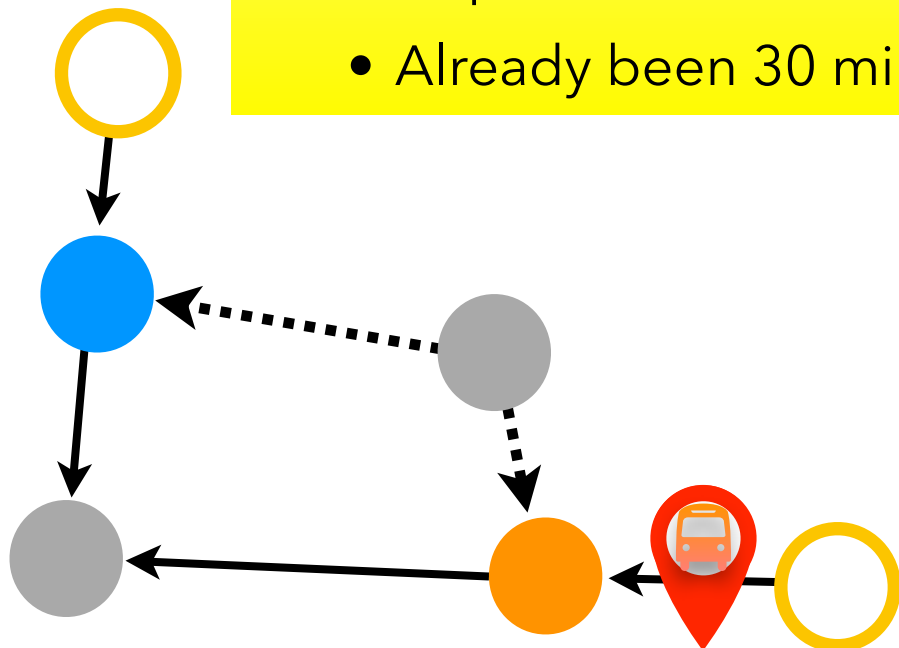
1. Adverse weather (e.g. snow) affect impedance and tiredness of road user with disability? **Weather** **Elevation**

3. Value of time when transit arrival delay cause potential delay for doctor's appointment **Time Delay** **Weather** **Elevation**

- Relative importance of time is more important than tiredness

5. Unexpected construction make quick route non-traversable **Time Delay** **Weather** **Elevation**

- Already been 30 mins, and another 30 min or 10 min with high slope? **Construction**

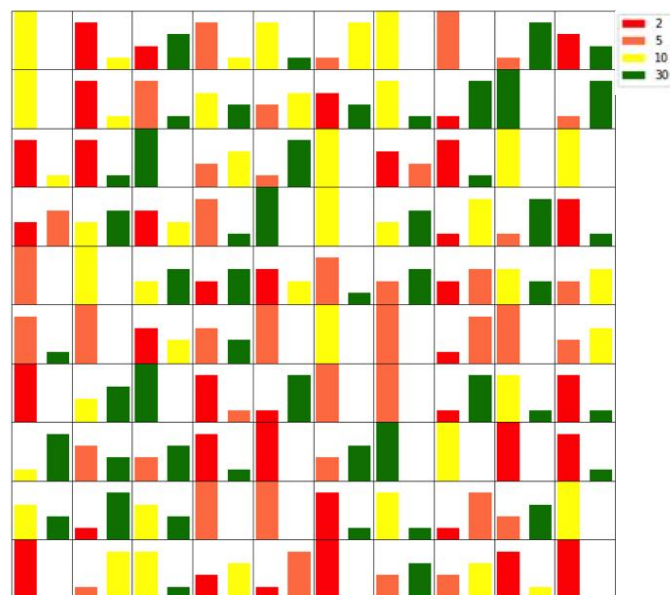
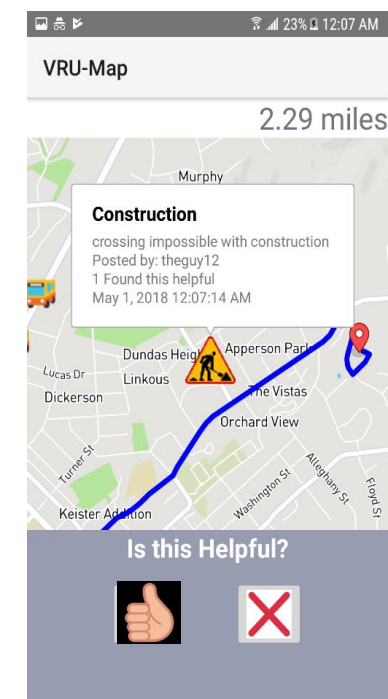
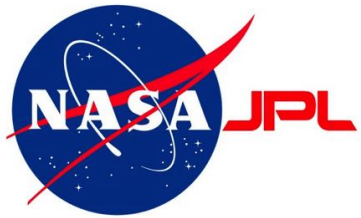




CASE STUDY FOR PEOPLE WITH DISABILITIES

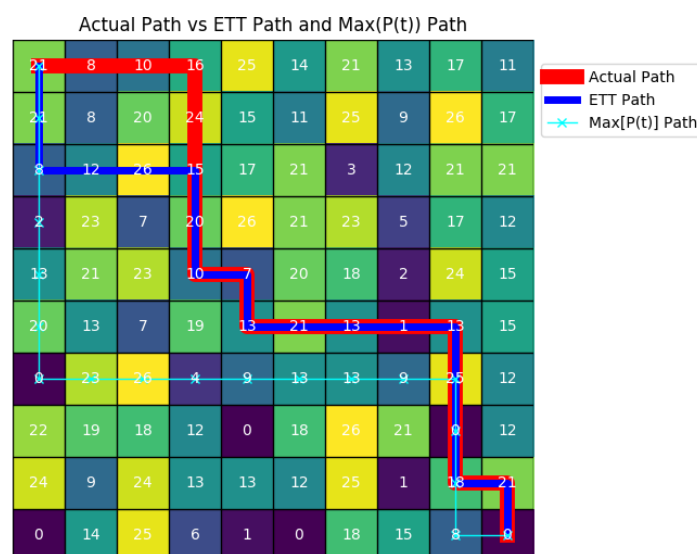
★ Current databases are not sufficient for all users' needs
Crowdsourcing allows for additional information

★ Probabilistic distribution of travel time for formulating the best options to travel with partial, sequential, and mixture of information gain



★ Images of the sidewalk network from the satellite provides some sort of secondary data which has an associated uncertainty.

★ Incorporated in estimating the parameter for the surface condition that a traveler may encounter with some certainty by using that path.



★ Utility Function based path vs two theoretical paths: minimize initial Expected Travel Time (ETT) vs Max[P(T)] (highest probability classification)-based travel time.

★ grid each cell type by number (white), filled color.

★ The highest information gain is achieved by visiting the maximum number of different cell types.

DYNAMIC TRANSIT MODELING

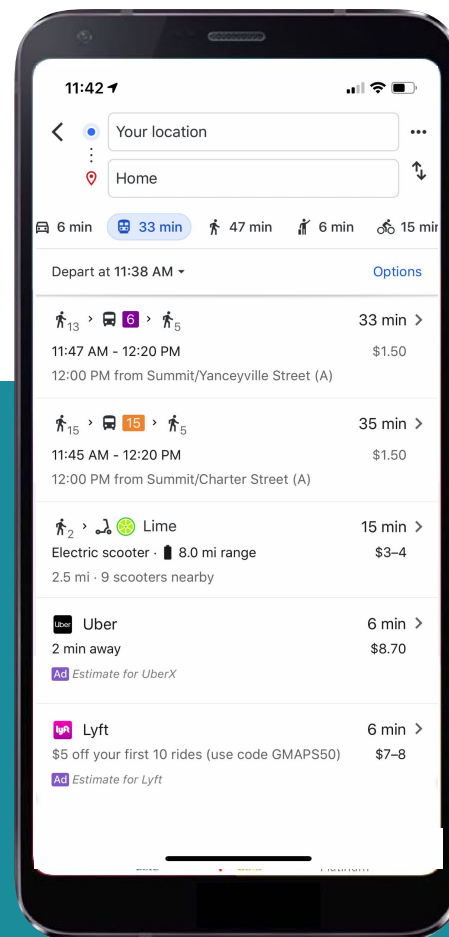


- Inform transit drivers 'pick-up change' through cell phone cloud source



Transit System

Balance between transit time with/without riders efficiently pick-up and drop-off passengers while considering **dynamic** change.



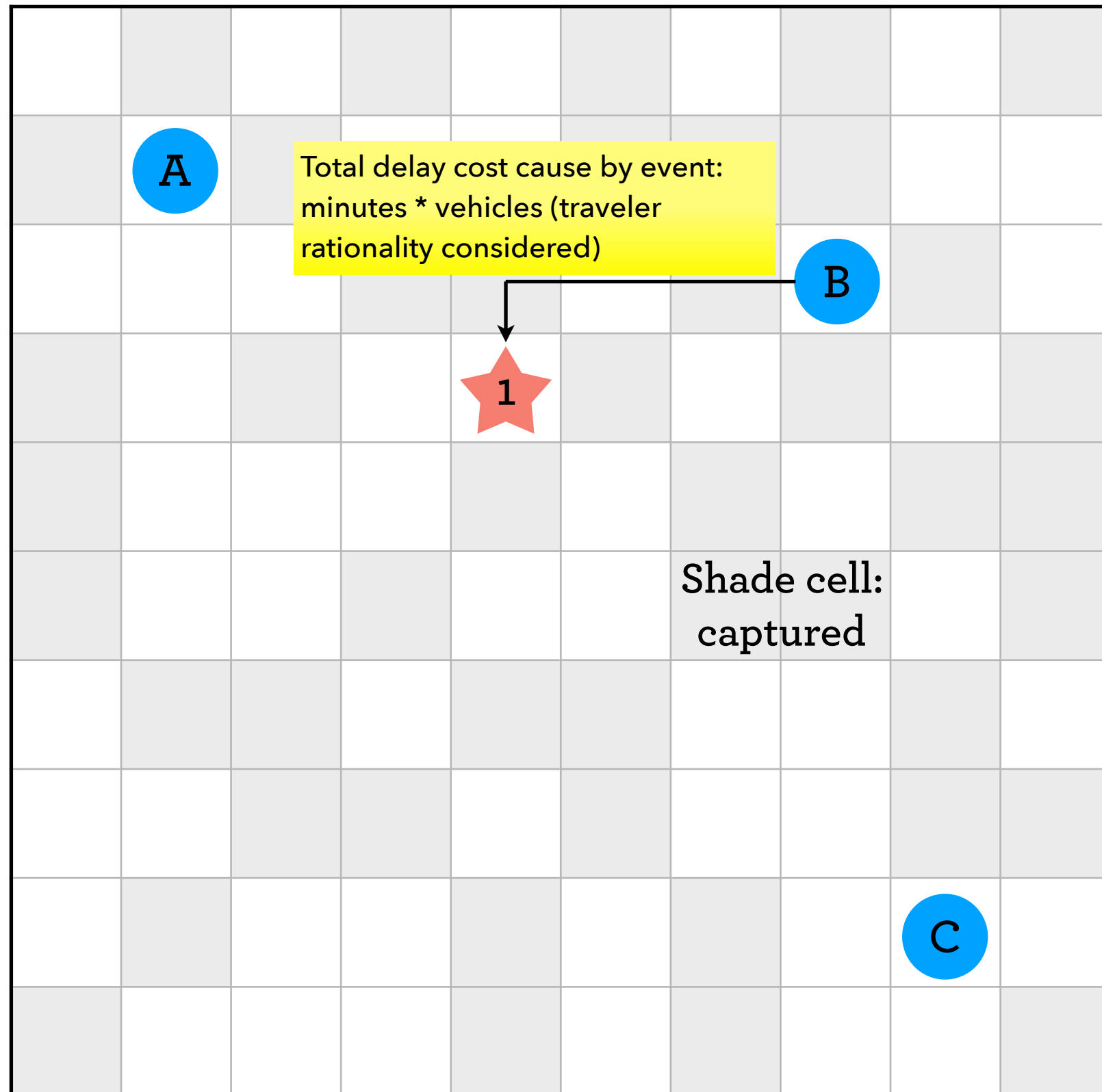
Road User

Maximize **individual** user social **surplus** considering the bounded rationality

SUCCESSFUL SERVICE OPERATION

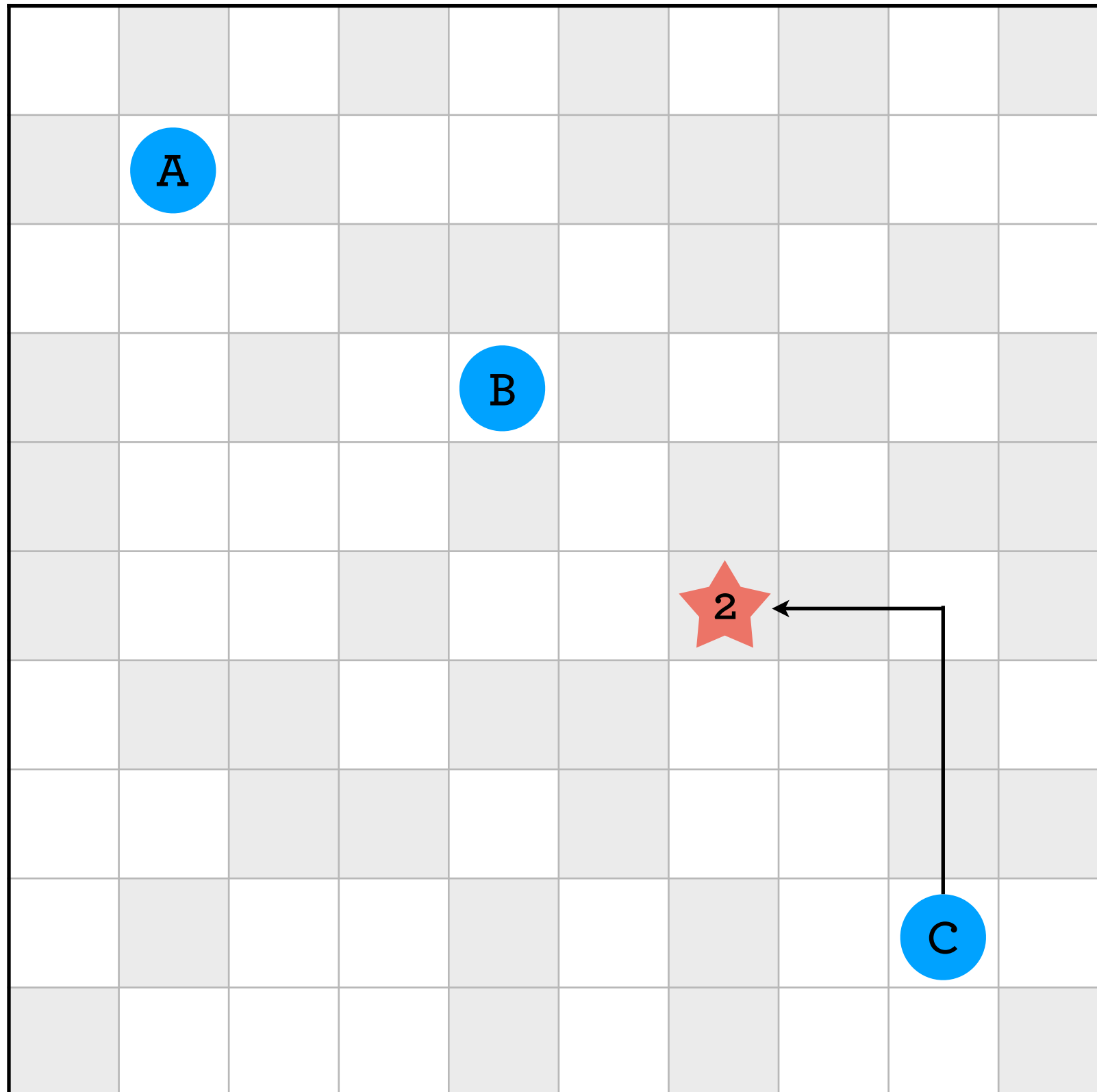
★ To be applied to transit operation - [Predictive operation based on traveler choice on TransModeler](#).

- Published Transportation Research Part C & TRB 2019 Annual Meeting, # 19-05975



SUCCESSFUL SERVICE OPERATION

★ To be applied to transit operation - Predictive operation based on traveler choice on TransModeler.



★ Modeling a driver behavior in TransModeler using Driver Groups option

Driver Groups

Driver Group Parameters

Driver Group	Uninformed	Informed
Fraction of population	0.50	0.50
Informed	<input type="checkbox"/>	<input checked="" type="checkbox"/>
Relative travel time	-2.1500	-2.1500
Travel time (1/min)	-0.0500	-0.0500
Non-freeway length (/miles)	0.0000	0.0000
Freeway length (/miles)	0.0000	0.0000
Controlled intersections	0.0000	0.0000
Different from current path	-0.0100	-0.0100
Value of time distribution	High Income	High Income
Value of time (\$/hr) *	25.00	25.00
Toll cost (1/\$) **	-0.0020	-0.0020
Choice set threshold (%)	50.0	50.0
Update delay threshold (%)	5.0	5.0
Reroute bias horizon (min)	10	30
Reroute threshold (%)	-0.06	-5.00

* The mean value of time for distribution chosen for this group.

** Ratio between Value of Time and coefficient for Travel Time.

Path-size Gamma

Rerouting in Response to High Delay

Step size for evaluating reroute alternatives (sec)

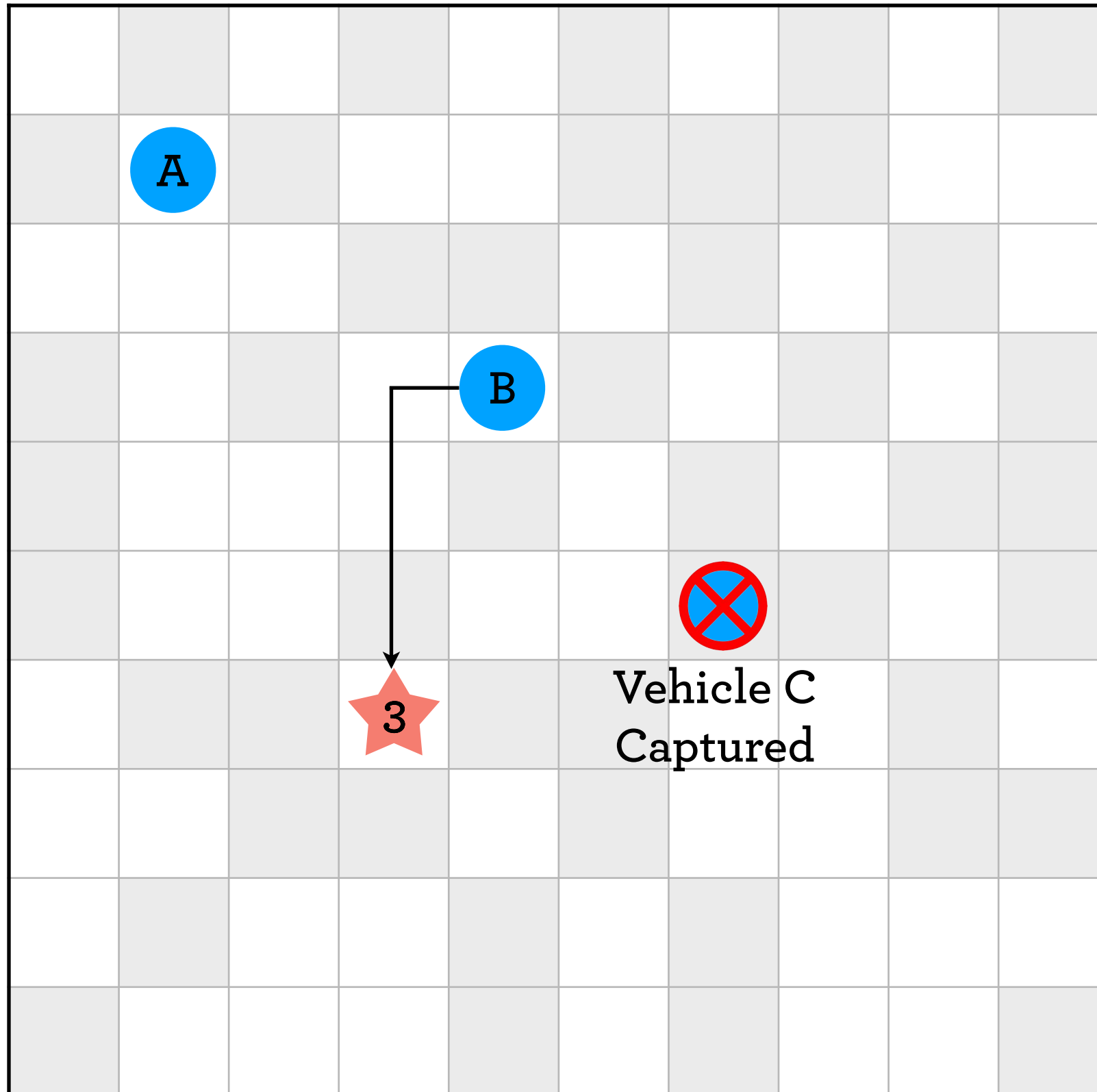
Maximum bias against current path (%)

★ Path-Size Logit model - calculate the probability of the travelers switching to alternative routes

$$P(i|C_n(t)) = \frac{e^{V_{in}(t) + \ln PS_{in}}}{\sum_{j \in C_n(t)} PS_{jn} e^{V_{jn}(t)}}$$

SUCCESSFUL SERVICE OPERATION

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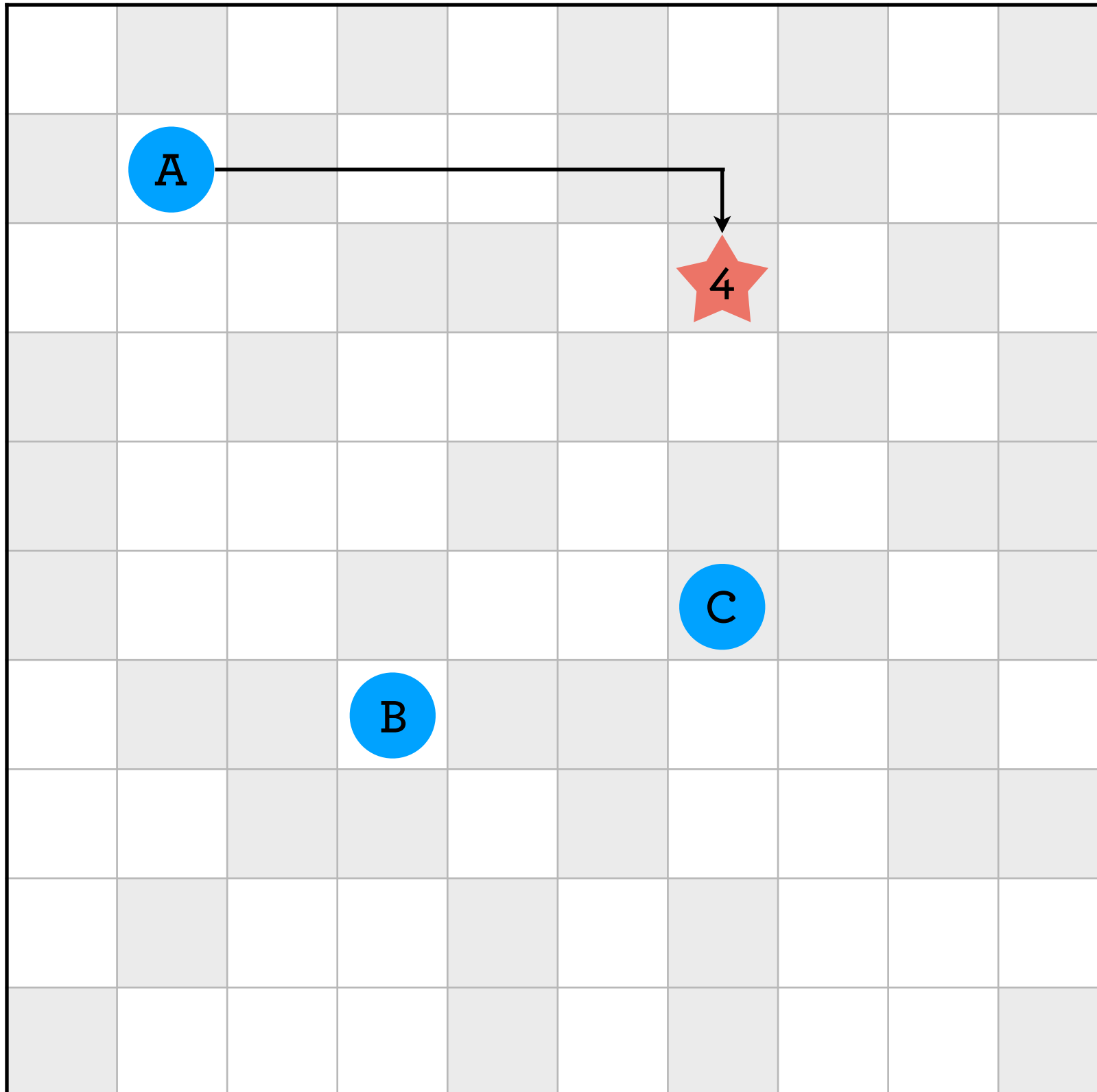
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SUCCESSFUL SERVICE OPERATION

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Informed	<input type="checkbox"/>	<input checked="" type="checkbox"/>
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Travel time (1/min)	-0.0500	-0.0500
Non-freeway length (/miles)	0.0000	0.0000
Freeway length (/miles)	0.0000	0.0000
Controlled intersections	0.0000	0.0000
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SUCCESSFUL SERVICE OPERATION

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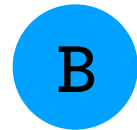
Vehicle A
Captured



5



B



★ Modeling a driver behavior in TransModeler using Driver Groups option

Driver Groups

Driver Group Parameters

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Fraction of population	0.50	0.50
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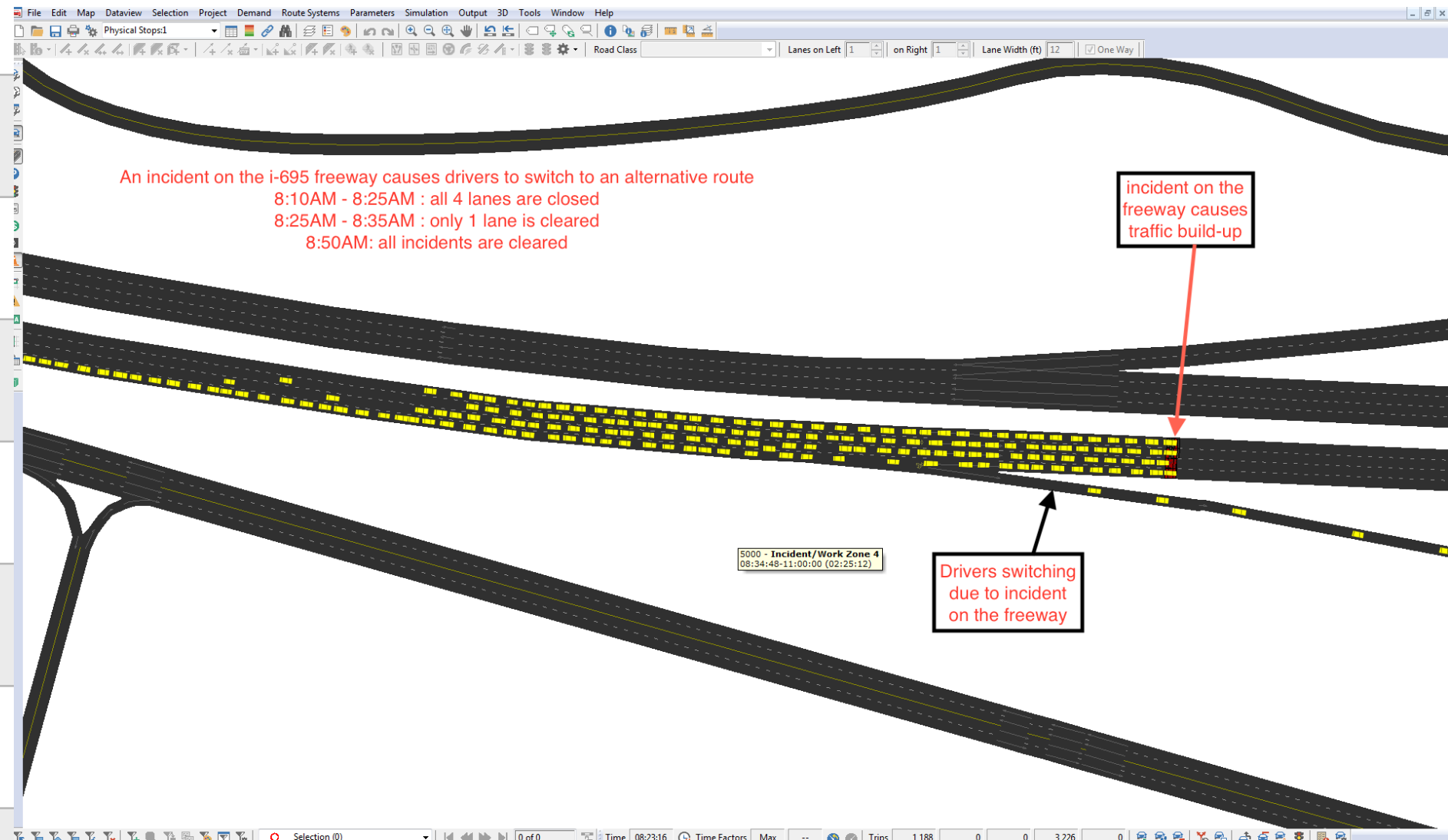
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SUCCESSFUL SERVICE OPERATION

★ To be applied to transit operation - Predictive operation based on traveler choice on TransModeler.

★ Dynamic Stochastic User- Equilibrium assignment considered - TransModeler

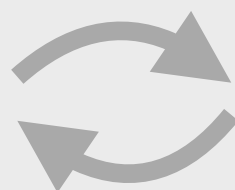


TASK 3: INCENTIVE OPTIMIZATION

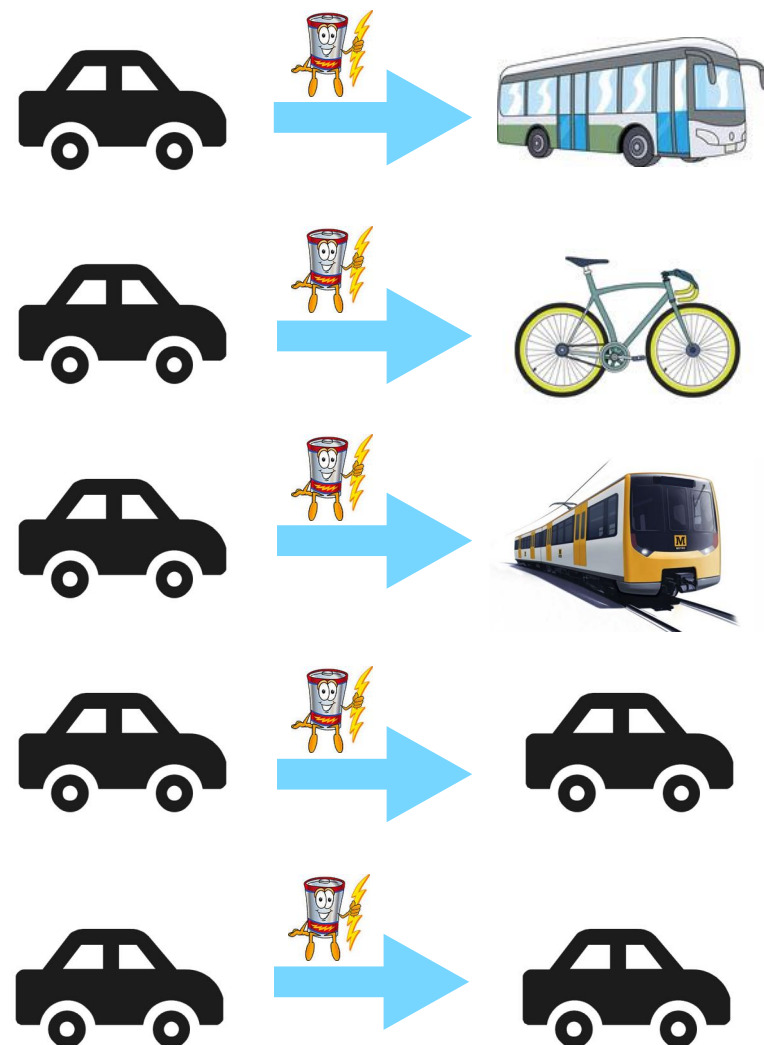
System Optimization



Optimal



User Optimization

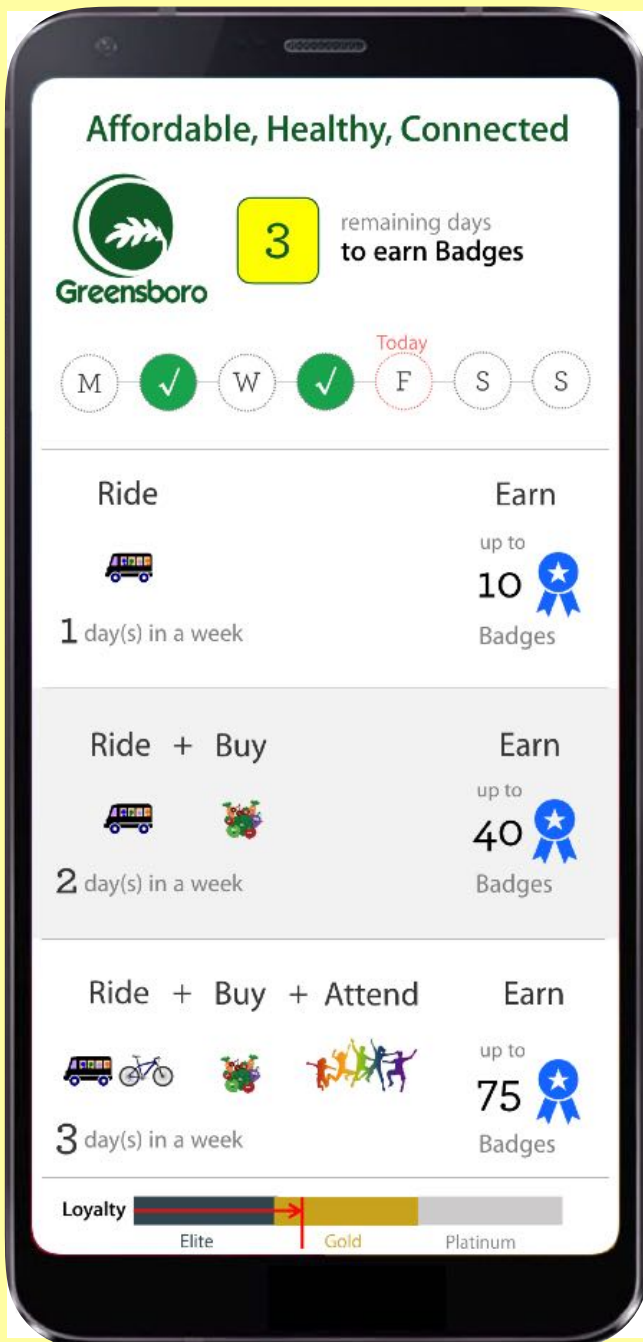


Different Mode

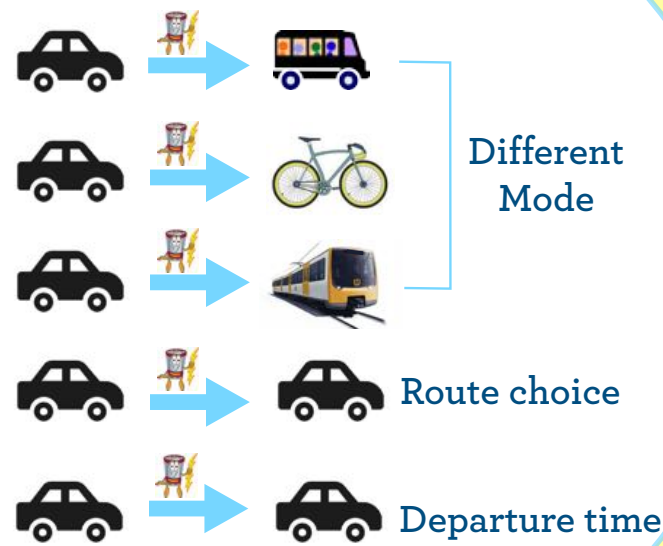
Route choice

Departure time

(a) Incentive Optimization



(b) User Optimization



Control Architecture \leftrightarrow System Model

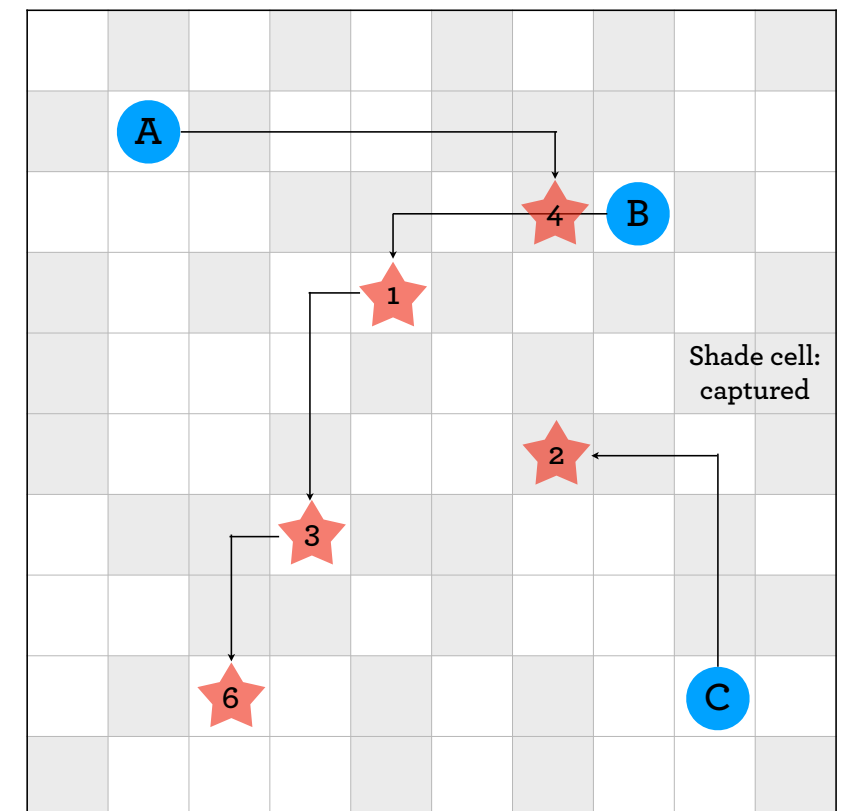
Preference \leftarrow

\rightarrow Reward

Experienced network condition

Travel choice \rightarrow

(c) System Optimization



Real-time energy savings \rightarrow

Thank you for
your attention
Q & A
hparkl@ncat.edu



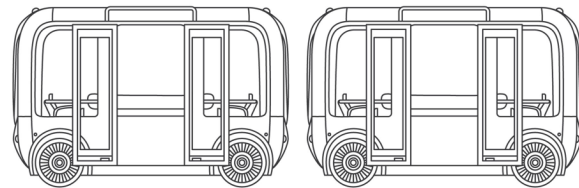


NORTH CAROLINA

Department of Transportation



The Olli's are Coming!



Stephanie L. Sudano, P.E.

NCDOT Multimodal Special Projects Engineer

May 3, 2019

Imagine hopping onto a bus and **NOT** pulling out your phone to search for a place to eat, the weather forecast, or the closest coffee shop. Instead you ask your transport those questions.

We are imagining this and more in North Carolina as NCDOT plans for a pilot launch of self-driving cognitive vehicles called Olli's.

Meet **olli** by *local motors*



Self-driving, electric, cognitive (IBM Watson) shuttle, 3-D printed, Level 4/5 AV
25 mph maximum speed, seats 8-12 people

Coming this Fall

NCDOT has negotiated with Local Motors to bring two Ollis to NC.



NCDOT's pilot program will partner with local communities across North Carolina for a period of 24 month to deploy the Olli as a fixed-route transit circulator.



NC's Ollis
will be 3-D
printed in
October and
delivered in
November

More about the Olli



Ramping up for the Olli NC Campaign

Rural to Urban
Innovation
Outreach and Engagement
Technical Expertise

Statewide

Data Collection
Private then Public Streets
Collaboration

Customer Surveys
Diverse Environments
Communities

Why this project?

- Explore new transportation technology & innovative solutions
- Allow communities to experience new transportation technology
- Learn about the way this technology will change:
 - State and local transportation planning
 - Community planning
 - Perception of public transportation
 - Accessibility to transportation



Long-range Planning considerations:

- Impacts to public transportation
- Parking & urban street design
- Traffic signal timing
- Pedestrian interactions
- Impacts to industry
- Parking deck design
- More.....

The Olli Game Plan

(still under development)

Teams:



Olli NC Transit Deployment Team (ONC-TDT)

- NCDOT Division Leaders
- Crosscutting disciplines involved



Olli NC Technical Oversight Team (ONC-TOT)

- Small Internal Team
- Day to Day Oversight

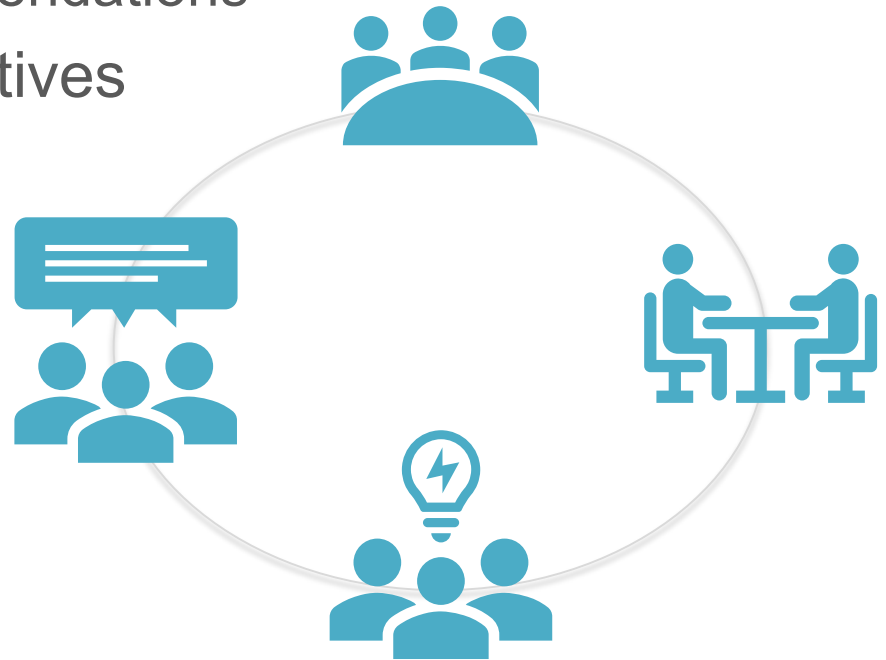


Olli NC Community Deployment Teams (ONC-CDT)

- Local leaders, city, town, and university leaders and staff members

Collaboration

- NC Fully Automated Vehicle Committee (FAV)
 - NCDOT CAV Roadmap
 - FAV Committee Recommendations
- Other AV and Transit Initiatives in NC
- Communities
- Universities
- Public Agencies
- And More...

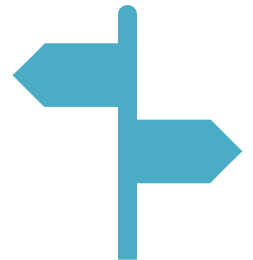
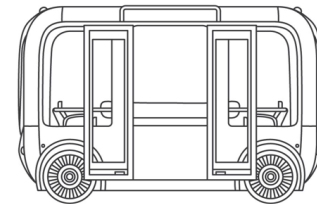
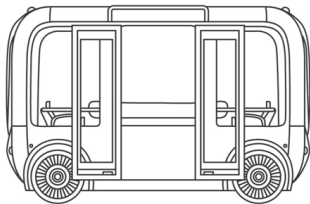


Project Delivery

- Phase 1: Selecting first two communities from existing list of use cases
- Phase 2: Invitation for submittal of more use cases

Timeline:

- October 2019 NC's Olli 3-D Printed
- November 2019 Olli NC Transit Deployment Phase 1 begins
- December 2019 Phase 2 begins
- November 2021 Olli NC Transit Deployment ends



Challenges

- Reaching and engaging Communities
- Funding
- Logistics of Multiple Pilot Locations
- Short-term Deployments (4-6 months)
- Diverse Demographics
- Public Perception/Reception



- Who knows what else?
This is NEW!



Contact:

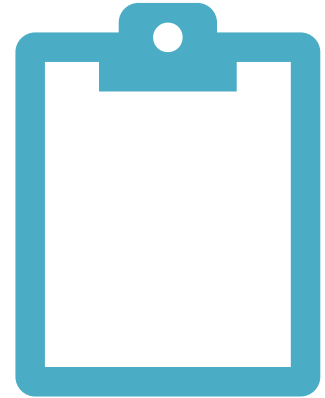
Stephanie L. Sudano, P.E.

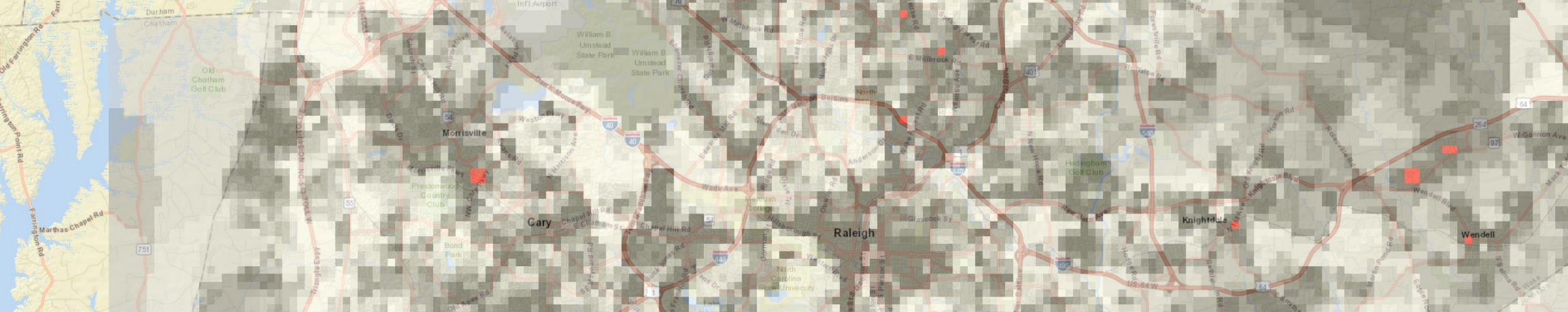
NCDOT Multimodal Special Projects Engineer

ssudano@ncdot.gov

919-707-2611

Interested in learning more?
Add your name to the sign up sheet to be notified
when the Olli NC Transit website is launched.





MAXIMIZING FIRST/LAST MILE TRANSIT ACCESS WITH A RASTER SUITABILITY ANALYSIS

PRESENTATION BY WESTON HEAD



THE FIRST/LAST MILE TRANSIT ACCESS PROBLEM



In order to use public transportation, the user needs to reach the station from his/her home and then reach his/her destination from the station

First and Last Mile access can be an issue in areas of low population density and with limited pedestrian and bicycle infrastructure

Many of the proposed solutions of this problem have shifted in recent years towards Mobility as a Service (MaaS) technologies





Image Source: Clark Nexsen, Prototype Bus Shelter

PROPOSED SOLUTION: OPTIMAL PLACEMENT OF TRANSIT STATIONS

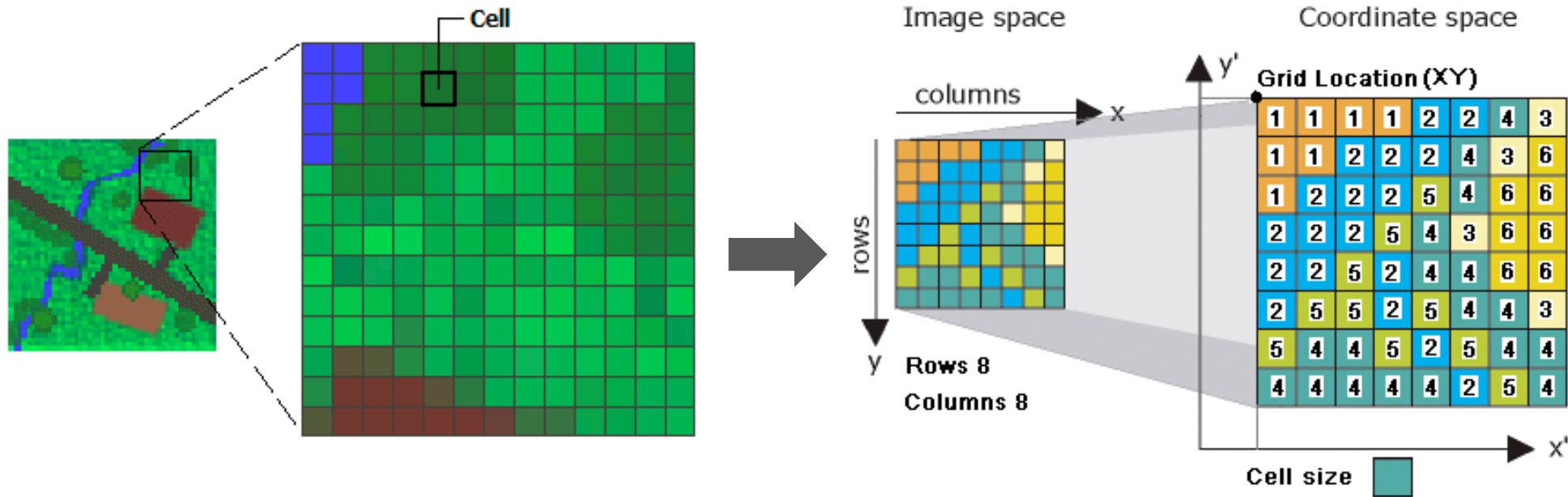
Focus on the placement of the transportation stations, not the resulting first and last miles

To maximize first and last mile transit access, a raster suitability analysis should be completed for the study area.

A raster suitability analysis will use quantitative data as inputs and output optimal locations for transit stations

The raster suitability analysis is consistent, repeatable, customizable, and based off of data.

RASTERS: BACKGROUND



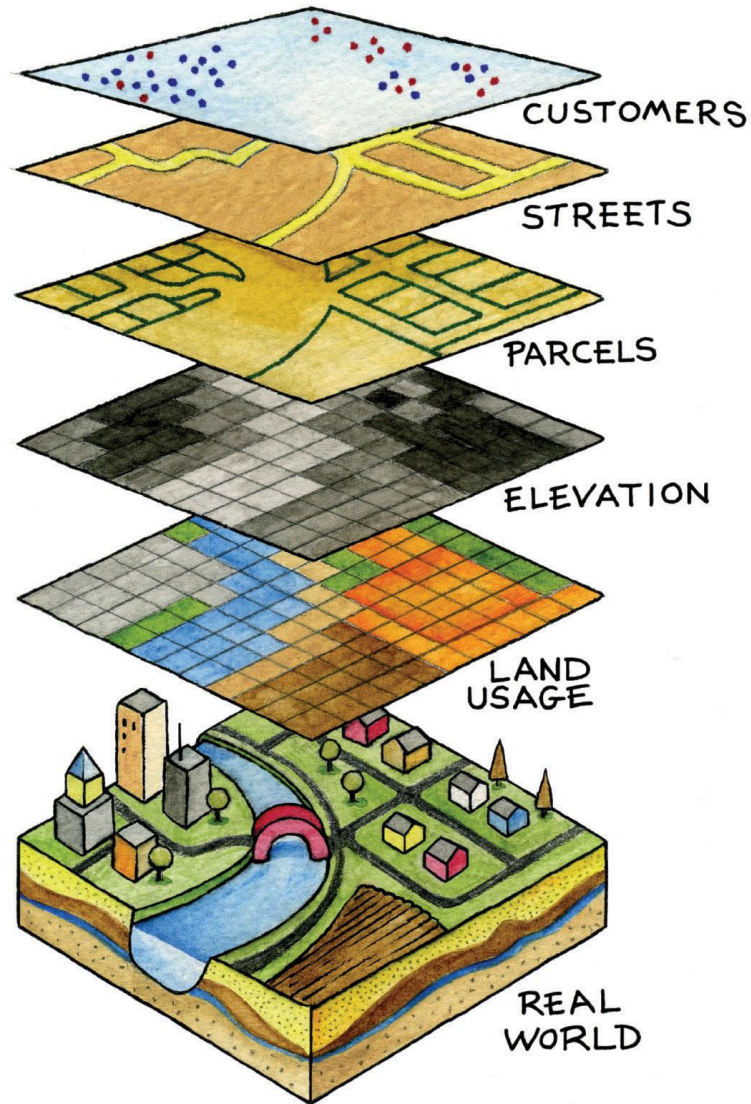
“In its simplest form, a ***raster*** consists of a matrix of cells (or pixels) organized into rows and columns (or a grid) where each cell contains a value representing information, such as temperature.”

–*ArcGIS Desktop Guide*



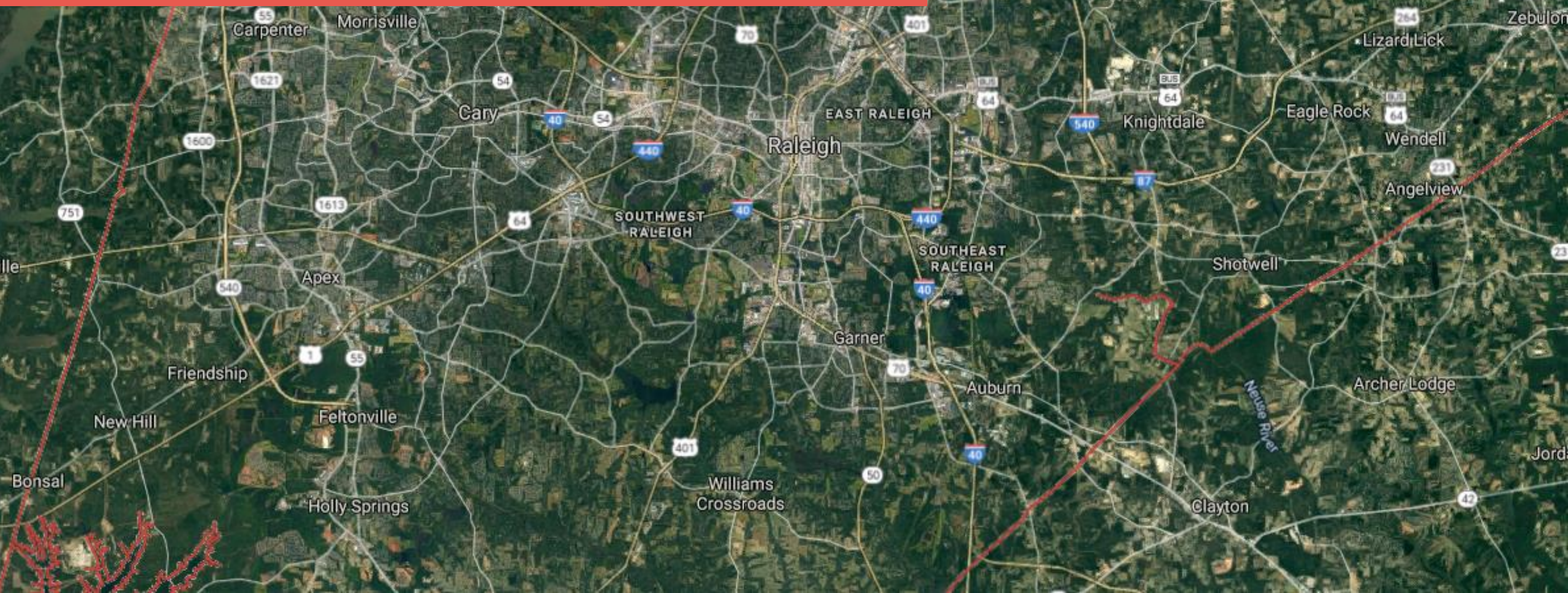
RASTER SUITABILITY ANALYSIS: BACKGROUND

Suitability Analysis combines multiple layers of quantitative data, standardizes it into a scoring system, sums them, and results in a raster layer containing values representing each raster's suitability.



PROCESS STEPS AND AN EXAMPLE

Define Your Problem and Area of Interest



- **Problem:** Placing bus stops in locations that will maximize first and last mile transit access while avoiding existing bus stop locations.
- **Area:** Wake County

DEFINE FACTORS OF IMPORTANCE

A Bus stop that maximizes last and first mile transit access should:

- Have close proximity to high densities of residents
- Have close proximity to high densities of commercial parcels
- Be far away from existing bus stop
- Have close proximity to areas with a low average household income
- Have close proximity to areas with a low average vehicle access per household

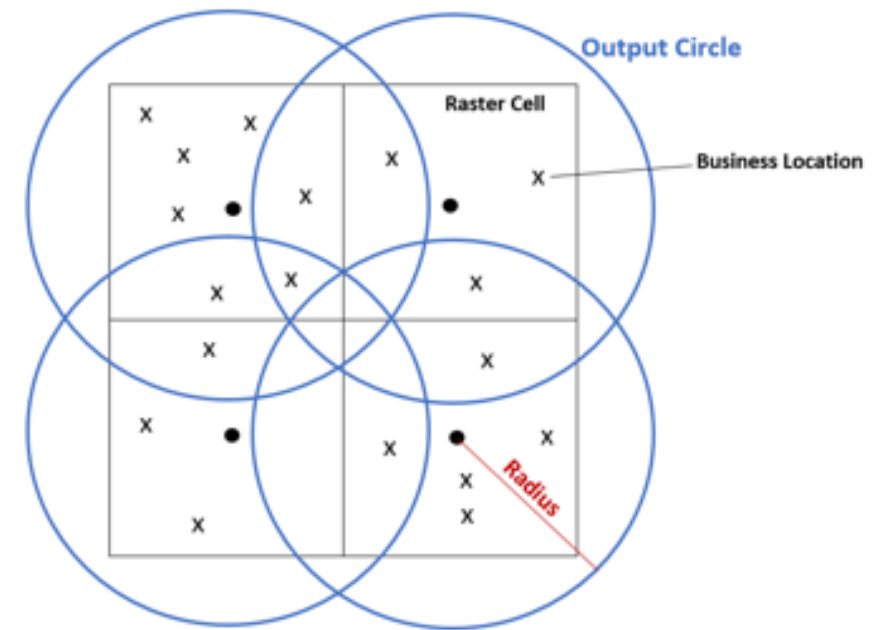
Others: (Not included in this example)

- Be located near schools, hospitals, libraries, etc.
- Be located near local bikeshare stations, train stations, other multimodal facilities
- ***Have anything else your research team or community thinks is important!***

GATHER DATA AND GEOCODE IT

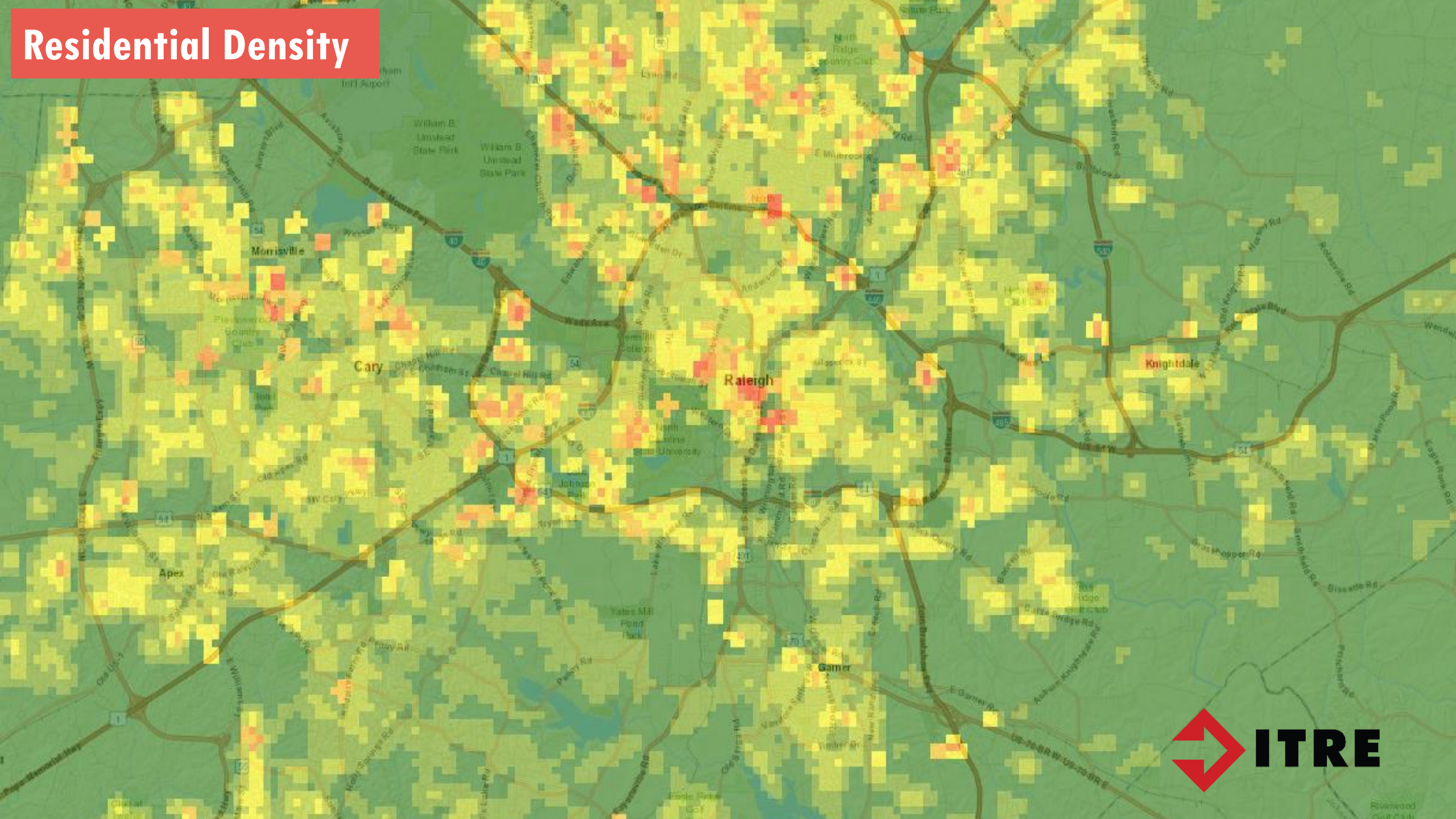
- For each factor, collect geo-located data that can be imported into GIS.
- Ideally, the data collected will already be a shapefile containing points or polygons
- Determine which quantitative method is appropriate for each field
 - Distance from each raster to a feature
 - Density of a feature within a distance of each raster
 - Average value of a feature around each raster

Point Density Functional Diagram



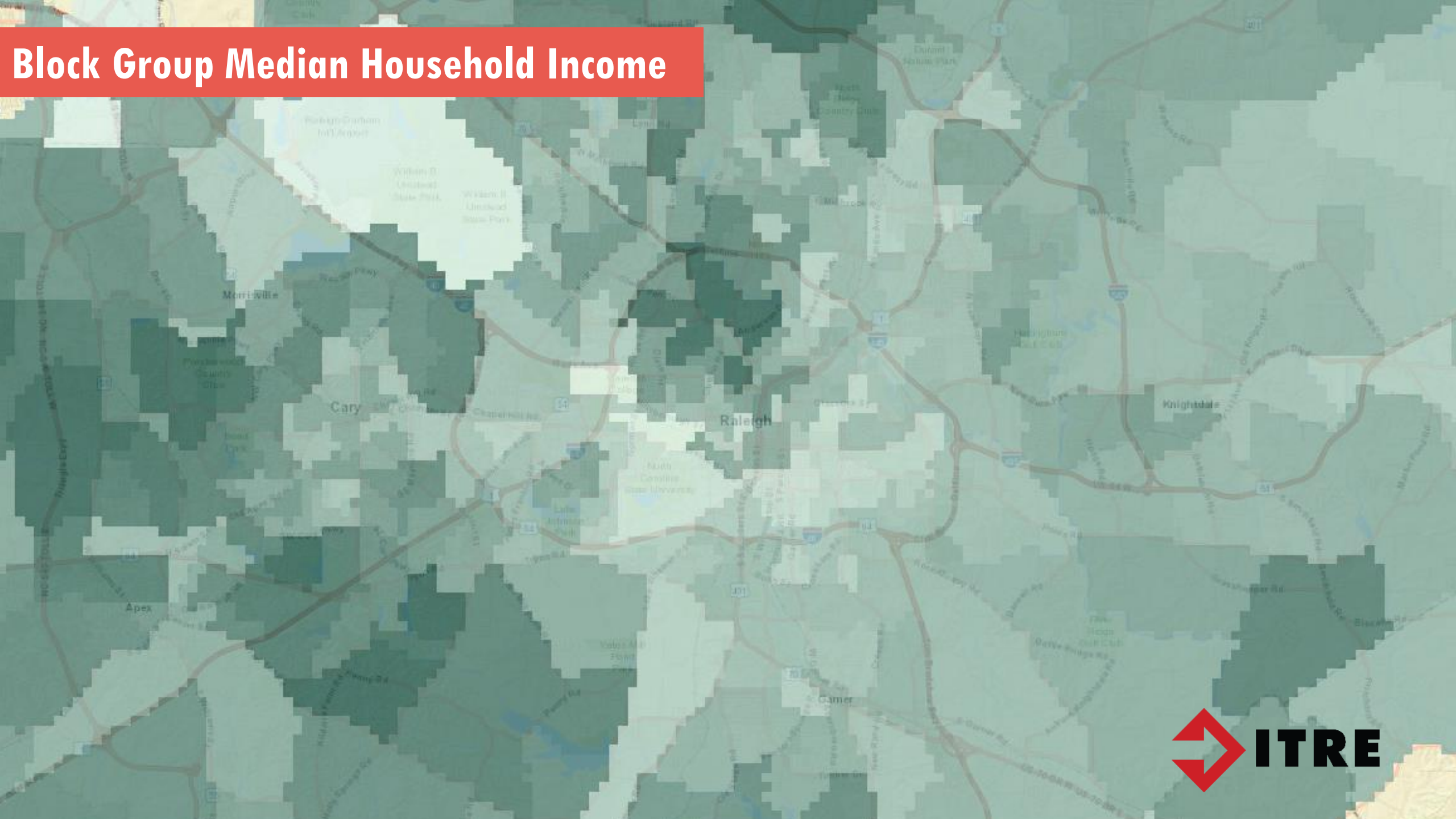
Information Source: ArcGIS Tool Reference,
How Point Density Works

Residential Density

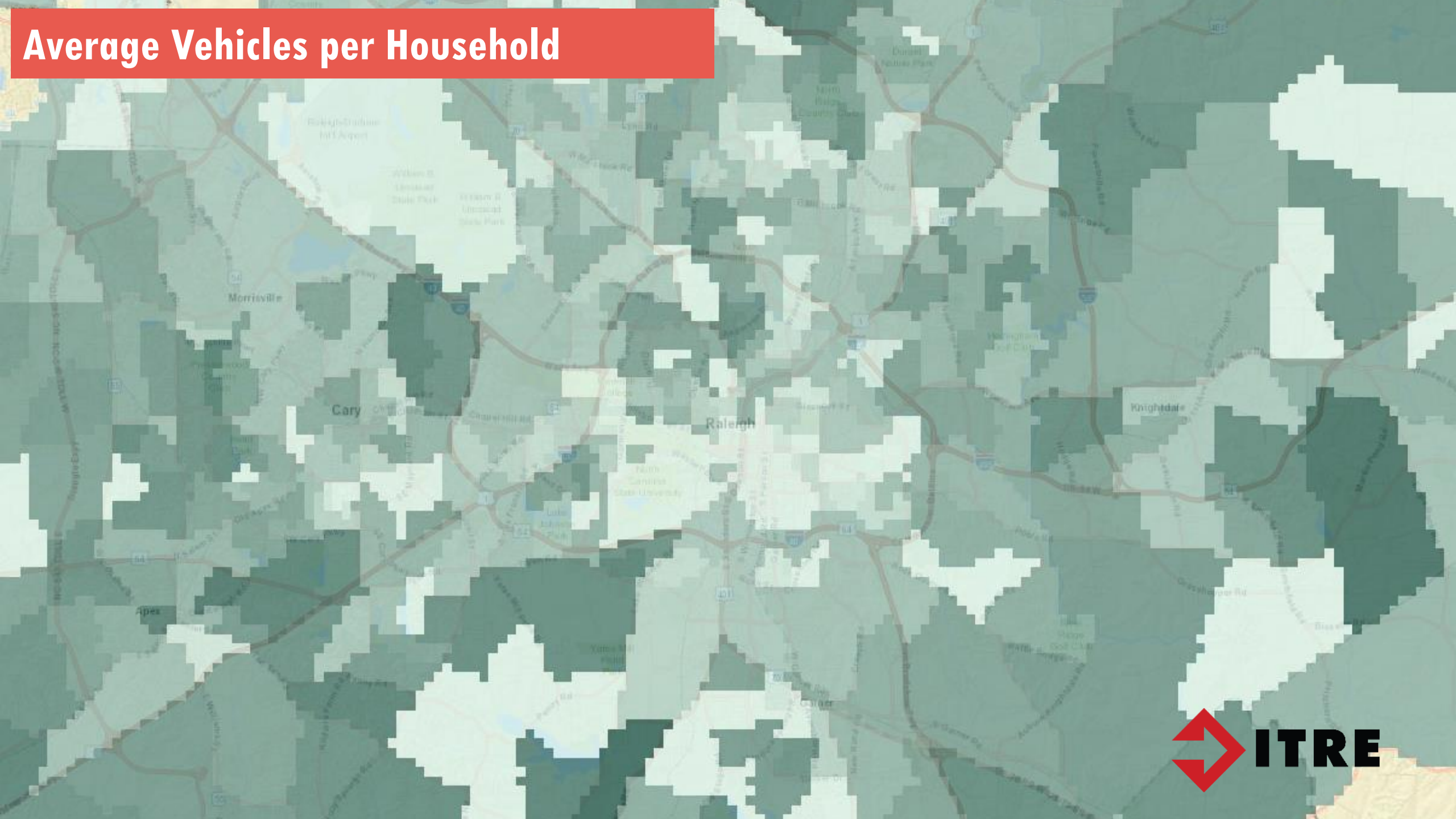


[illegible]

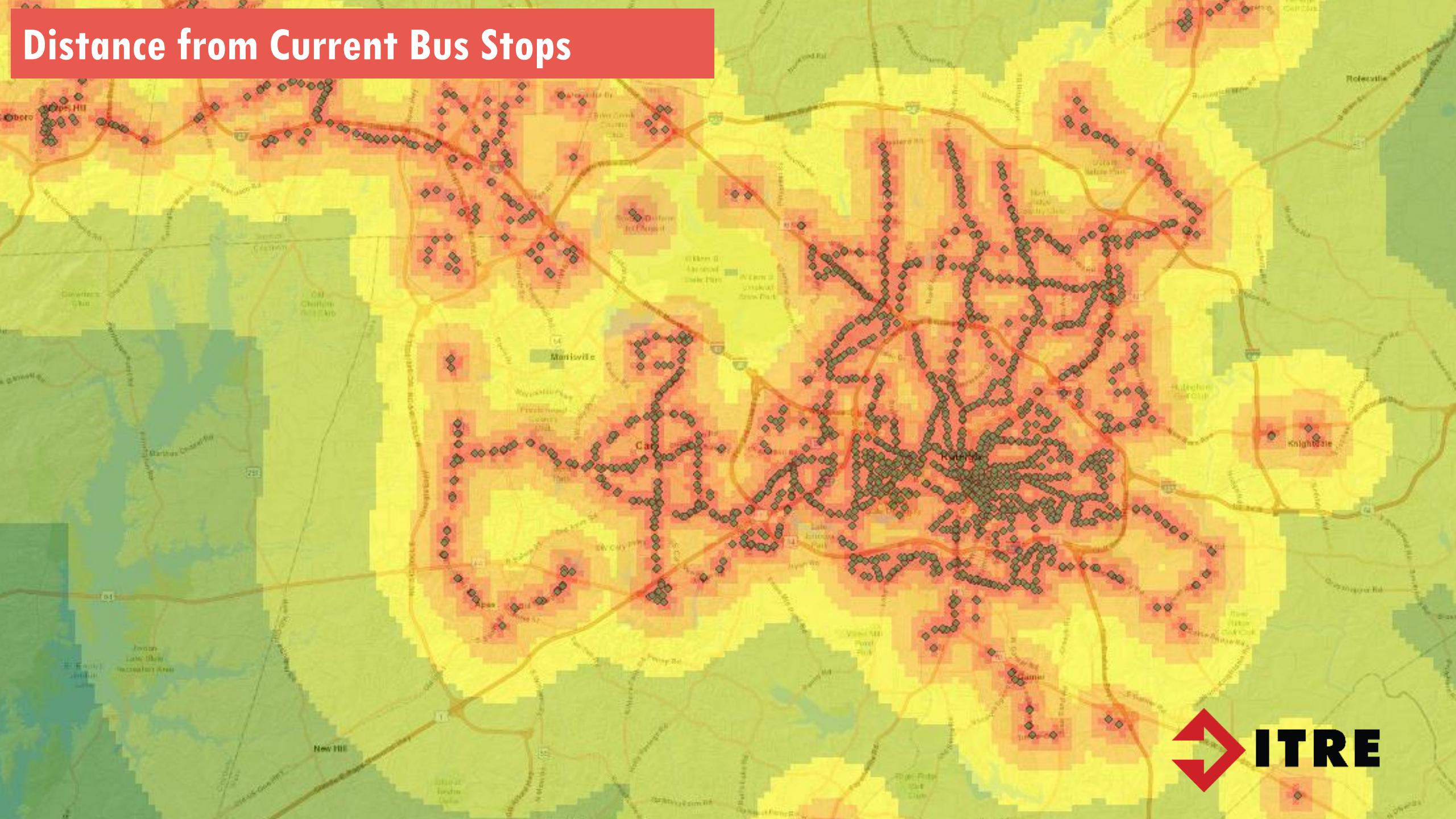
Block Group Median Household Income



Average Vehicles per Household

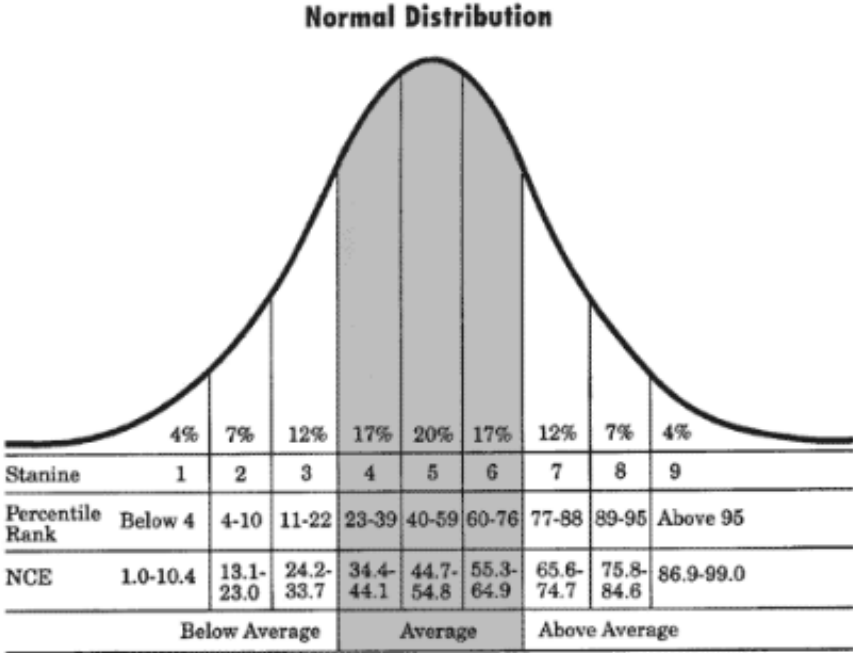


Distance from Current Bus Stops



STANDARDIZE AND WEIGHT EACH FACTOR

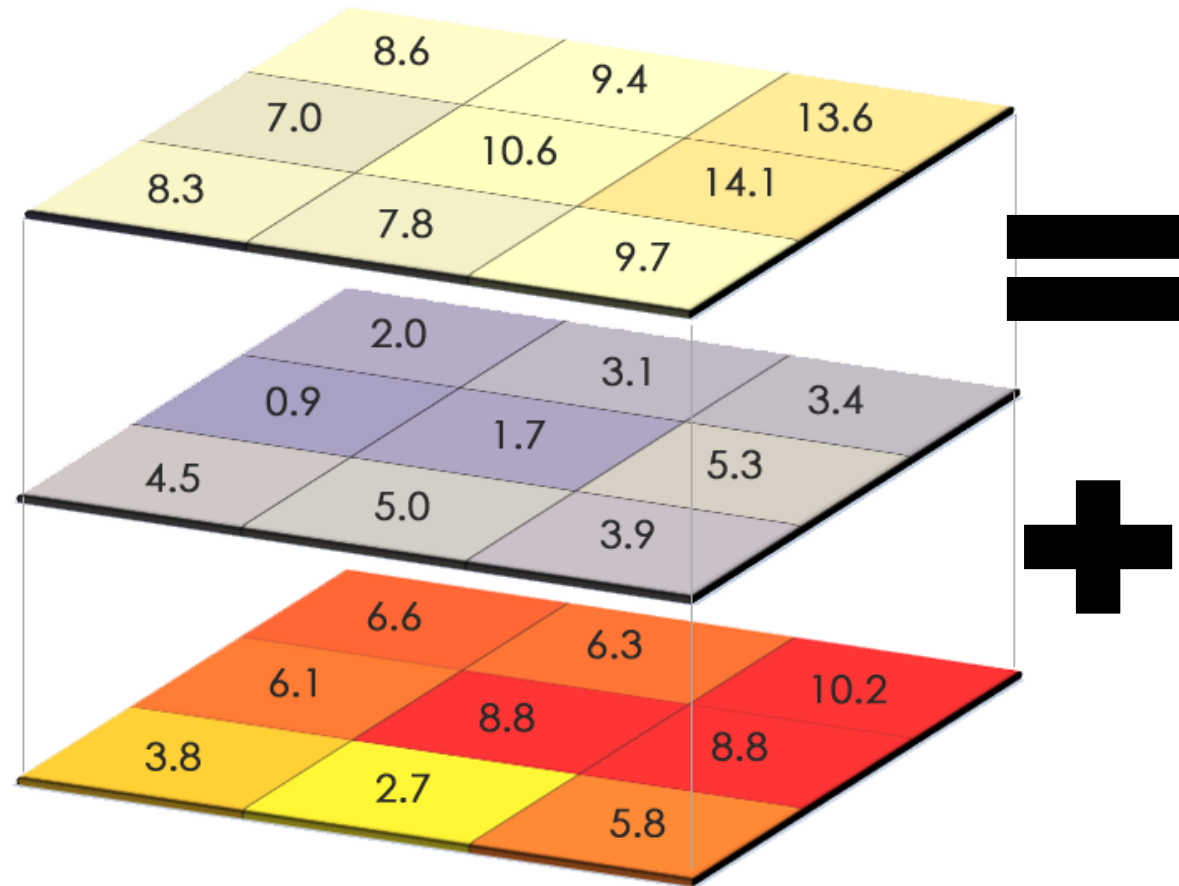
- In order to add the raster layers together, a common scale needs to be determined
- The scale can be based on quantiles, even interval, or by design
- Once each layers distributions have been converted into a scale, the factors should be weighted by importance
- The more important a factor is, the larger weight it should get



A Normal Distribution of Stanines, Percentile Ranks, Normal Curve Equivalents, and Performance Classifications



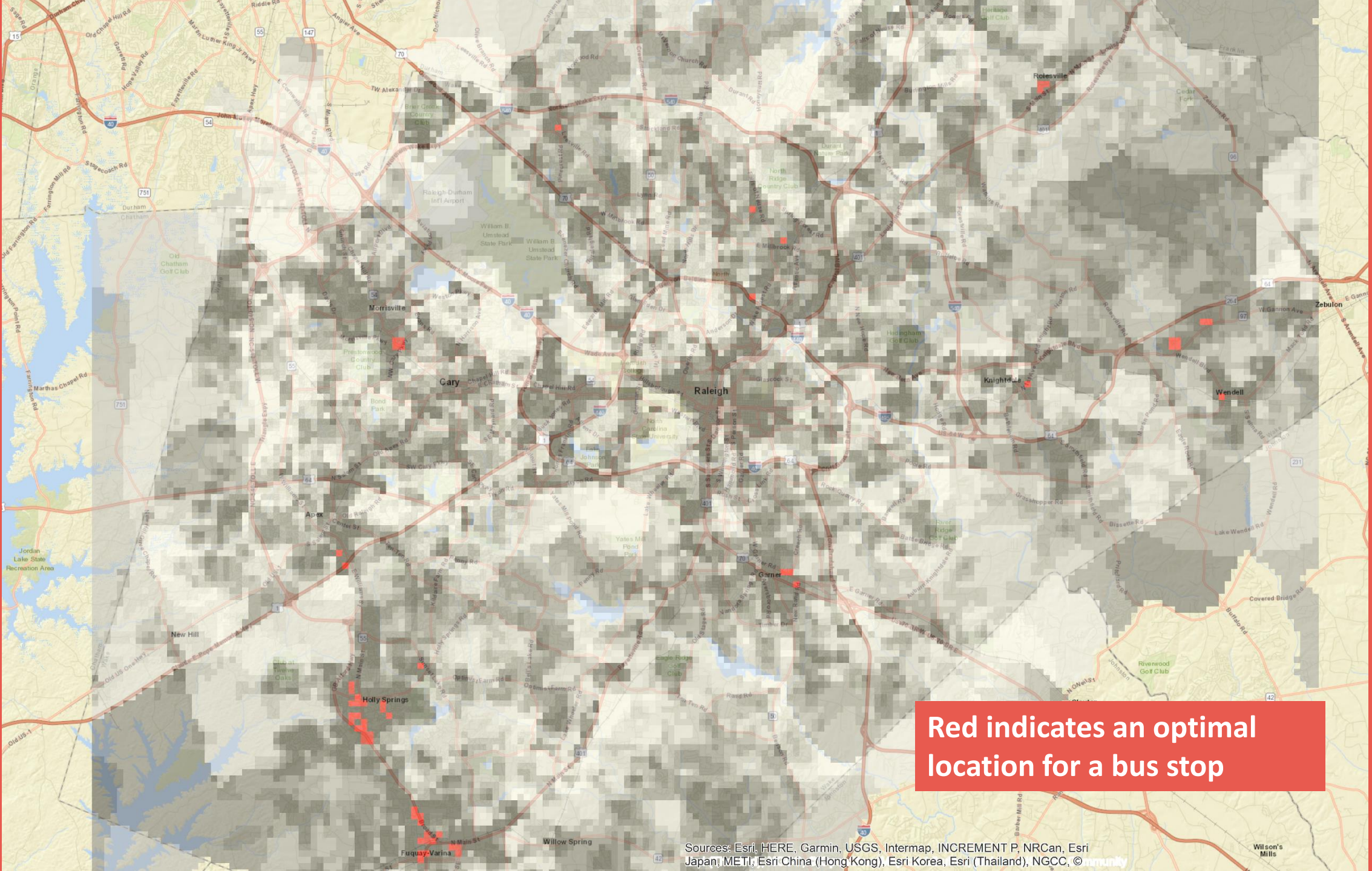
SUM THE RASTER LAYERS TOGETHER



RASTER SUITABILITY ANALYSIS: STEPS

- Define your problem and area of interest
- Define Factors of importance
- Gather geo-spatial data for each factor
- Perform raster analysis for each factor
- Standardize the raster analysis layer scales to a common scoring scale (i.e. 1 to 7)
- Determine weights for each variable raster layer based on importance
- Add together each weighted raster output layer to form one aggregate score per raster
- Choose the rasters with the highest scores as the optimal solutions

RESULTS



Red indicates an optimal location for a bus stop

BENEFITS OF THIS METHOD

- Can be implemented today, for any location
- Repeatable
- Data Driven
- Consistent
- Adaptable
- Creates the opportunity for community input

This suitability analysis currently only places stations, but does not provide any guidance on routes. It could be paired with origin and destination data to decide routes.





QUESTIONS?

Contact Information:

Weston Head

Research Analyst — Economics and Data

The Institute for Transportation Research and Education

wahead@ncsu.edu